DRAFT

STANDARD GEOSPATIAL SUPPORT DATA EXTENSIONS FOR THE NATIONAL IMAGERY TRANSMISSION FORMAT STANDARD

25 FEBRUARY 1997

FOREWORD

- 1. This document is approved for use by all deprtments and agencies of the Depart of Defense (DOD).
- 2. TBD
- 3. Beneficial comments (recommendations, additions, deletions) and any pertinent data which may be of use in improving this document should be addressed the National Imagery and Mapping Agency, Interoperability Branch (SEII), 14675 Lee Road, Chantilly, VA 20151-1715.

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1. SCOPE

- 1.1 <u>Scope</u>. This document specifies the format and content of a set of controlled tagged record extensions for the NITF. Detailed descriptions are provided for the overall structure, as well as specification of the valid data content and format, for all fields defined within each specified support data extension (SDE). In addition, technical information is presented to provide a general understanding of the significance of the included fields.
 - 1.2 Purpose. TBD
 - 1.3 Applicability. TBD

2. APPLICABLE DOCUMENTS

The applicable documents in section 2 MIL-STD-2500B apply to this document.

3. DEFINITIONS

The definitions in section 3 MIL-STD-2500B apply to this document.

4. GENERAL REQUIREMENTS

- 4.1 <u>Appropriate support data</u>. That set of support data needed to accomplish the mission of a system receiving a NITF file is referred to as "appropriate" support data. The appropriate support data may vary across systems receiving NITF files. A system receiving a NITF file may add or subtract support data before passing the file to another system with a different mission. This strategy implies a modular support data definition approach.
- 4.2 <u>NITF</u> file containing georeferenced image, matrix, or raster map data. Image and raster map providers produce NITF files with support data from other formats which also contain support information. The extensions described herein define the format for that support information required within a NITF file containing geo-referenced image, matrix, or raster map data such as that defined in the DIGEST standard. The specified tagged records incorporate all SDEs relevant to geo-referenced image, matrix, or raster map data such as that defined in the Digital Geographic Information Exchange Standard (DIGEST). The information which makes up the SDE is derived from referenced standards including DIGEST. Systems using DIGEST imagery, matrix, or raster map data formatted according to NITF should be designed to extract the needed data from the tagged records described herein. The categories of image items in a NITF file, to which the standard support extensions apply, are shown in table I.

TABLE I. Categories of image/matrix/grid data.

Categories of Image			Data extension to		image
Categories of mage/maths offa Data			Data extension to be included in the image subheader		
Definition	ICAT	IREP	ACCURACY	LOCATION	SOURCE
Raster Maps	MAP	MONO,	ACCPO	GEOPS	SOURC
1		RGB,	or	+ one of:	
		RGB/LUT	ACCHZ &	GEOLO	
			ACCVT	MAPLO	
				GRDPS	
				REGPT	
Definition	ICAT	IREP	ACCURACY	LOCATION	SOURCE
Geo-referenced	VIS, SL,	MONO,	ACCHZ	GEOPS	SNSPS
Imagery	TI, FL,	RGB,		+ one of:	
	RD, EO,	RGB/LUT,		GEOLO	
	OP, HR,	MULTI		MAPLO	
	HS, CP,			GRDPS	
	BP, SAR,			REGPT	
	IR, MS				
Matrix Data	DTEM	1D, ND	ACCPO	GEOPS	SOURC
(elevations)			or	+ one of:	
			ACCHZ &	GEOLO	
			ACCVT	MAPLO	
				GRDPS	
				REGPT	
Matrix Data	MATR	1D, ND	ACCPO	GEOPS	SOURC
(other)			or	+ one of:	
			ACCHZ &	GEOLO	
			ACCVT	MAPLO	
				GRDPS	
				REGPT	

4.3 <u>Georeferenced image, raster map, matrix, or grid data SDEs</u>. The following SDEs are defined for use with geo-referenced image, raster map, matrix, or grid data:

a. For spatial location:

GEOPS	for geo-referencing parameters including datums, ellipsoids, and projections
GRDPS	for non-rectified image, raster, or matrix data that is positioned using a location grid
GEOLO	for image, raster, or matrix data rectified consistently with geographic (lat/long)
	coordinate systems
MAPLO	for image, raster, or matrix data rectified consistently with cartographic (E,N)
	coordinate systems
REGPT	for registration points in either geographic or cartographic systems

b. For positional accuracy:

ACCPO	for horizontal and vertical accuracy over regions for which the definitions are constant
ACCHZ	for horizontal accuracy when the vertical accuracy vary across the region for which
	horizontal accuracy are constant
ACCVT	for vertical accuracy when the horizontal accuracy vary across the region for which
	vertical accuracy are constant

Positional accuracy description is required when spatial location is defined.

c. For source description:

SNSPS for sensor parameters SOURC for map source information

5. DETAILED REQUIREMENTS

- 5.1. Generic tagged extension mechanism. The tagged record extensions defined in this document are "controlled tagged record extensions" as defined in paragraph 26b of the NITF standard. The tagged record extension format is summarised here for ease of reference. Table II describes the general format of a controlled tagged record extension. The CETAG, CEVER, and CEL fields essentially form a small (11 byte) tagged record subheader. The format and meaning of the data within the CEDATA field is the subject of this document for several individual controlled tagged record extensions. Multiple tagged extensions can exist within the tagged record extension area. There are several such areas, each of which can contain 99,999 bytes worth of tagged extensions. There is also an overflow mechanism, should the sum of all tags in area exceed 99,999 bytes. The overflow mechanism allows for up to one gigabyte of tags. While the extensions defined in this document will typically be found in the image subheader (IXSHD field), it is possible that they could appear in a Data Extension Segment which is being used as an overflow of the image subheader.
- $5.2 \, \underline{\text{Field types}}$. If the information contained within an extension is not available, the extension will not be present in the file. For example, if positional accuracy is homogeneous across the whole data set extension, then the Horizontal and Vertical Accuracy Records will not appear since all of the accuracy will be contained in the Positional Accuracy Record. When an extension is present, all of the information listed as Required (type = R) must be filled in with valid information.

TABLE II. Controlled tagged record extension format (TYPE "R" = Required "C" = Conditional)

	· 1 · · · · · · · · · · · · · · · · · ·			
FIELD	NAME	SIZE	VALUE RANGE	TYPE
CETAG	Unique Extension Type Identifier. This field shall contain	6	(BCS-A)	R
	a valid alphanumeric identifier properly registered with			
	the control authority (TBR).			
CEL	Length of CEDATA Field (Number of Bytes). This field	5	(BCS-N)	R
	shall contain the length, in bytes, of the data contained in		00001 to 99988	
	CEDATA. The tagged record's length is 11 + the value			
	of CEL.			
CEDATA	<u>User-defined Data</u> . This field shall contain data of either	Value	User-defined	R
	binary or character data types defined by and formatted	of the		
	according to user specification. The length of this field	CEL		
	shall not cause any other NITF field length limits to be	\mathbf{field}^*		
	exceeded but is otherwise fully user defined.			

APPENDIX A

SPATIAL DATA EXTENSIONS

A.1 SCOPE

This appendix is intended to describe the standard support data extensions (SDEs) used to properly transfer geospatial information to provide accuracy, and coordinate data. The nature of raster data is inherently different than vector data because the pixel representations are rows and columns which means the surface of the earth is being mapped to some type of rectangular grid. Map makers have faced this challenge since the beginning of their profession and many solutions have been put forth to project the spheroidal geometry of the earth to a flat surface such as a paper map. Images of the earth's surface inherit additional complexities due to the look angle of cameras and the other imaging parameters such as focal length, atmosphere refraction, etc.

A.2 APPLICABLE DOCUMENTS

STANAG 7074/AGeoP-3A - Digital Geographic Information Exchange Standard (DIGEST). Edition 1.2a, June 1995.

A.3 DEFINITIONS

The definitions in section 3 MIL-STD-2500B apply to this appendix.

A.4 GENERAL REQUIREMENTS

- A.4.1 <u>Approximate geographic location</u>. The IGEOLO and ICOORDS field in the image subheader shall only be used for coarse representation of the geographic or cartographic coordinates of the image.
- A.4.2 <u>Accurate geographic location</u>. The specified tagged records incorporate all SDEs relevant to geo-referenced image, matrix, or raster map data such as that defined in the Digital Geographic Information Exchange Standard (DIGEST). The information which makes up the SDE is derived from referenced standards including DIGEST. Systems using DIGEST and/or NIMA's imagery, matrix or raster map data formatted according to NITF should be designed to extract the needed data from the tagged records described herein.

A.4.3 Coordinate systems.

- A.4.3.1 <u>General</u>. Most people are familiar with the concept of latitude and longitude for locating places on the face of the earth. Most people have also used graph paper to lay out a garden or house plan where distance left-right and up-down are so many grids cells or simple (x-y) orthogonal measurements in inches or centimetres. These principles for coordinates apply in the geospatial sense but more detail is needed to insure data transfer carries the meaning intended by the transmitter to the receiver.
- A.4.3.2. <u>Coordinate system types</u>. Three types of coordinate systems are defined for geospatial information: (1) Geographic (GEO), (2) Cartographic (MAP), and (3) Relative (DIG).
- A.4.3.2.1 <u>GEO</u>. Geographic coordinates are expressed in latitude and longitude and are based on a geodetic datum, including both the geodetic ellipsoid and zero meridian. For the purposes of this standard, the zero meridian will default to GREENWICH (zero degrees longitude). Datums and ellipsoids are carried in the GEOPS extension. DIGEST lists more then 200 different datums. There are so many datums because geodesy continues to refine the understanding of the shape and gravity of the earth. As these refinements mature, maps and other spatial data tend to reflect the best knowledge available at the time the maps and/or data were produced. To properly interpret coordinates one must take into account the mathematics in effect at the time of production. It is often necessary to convert coordinates to a common coordinate system when using data produced in different time frames or by different organisations. Ellipsoids go along with many datums, but DIGEST lists fewer than 60 different ellipsoids. This is because many local datums exist without reference to an

ellipsoid but all global coordinate systems use an ellipsoid. Modern mapping prefers the ellipsoid and datum to be consistent with the World Geodetic System 1984 (WGS84).

- A.4.3.2.2 MAP. When using a cartographic coordinate system a location is specified as being so many units North/South (Northing) and so many units East/West (Easting) from a reference point within a defined projection plane. The projection is a mathematical relationship that defines a one-to-one mapping between the geodetic ellipsoid and the projection plane. A cartographic coordinate system is based on a projection (with values for all its associated parameters) applied to a geodetic datum (see above). The projection parameters are described in the GEOPS extension. DIGEST lists approximately 20 different projections and they require from one to four parameters. Note: The cartographic coordinate system may not be described using only PROJECTION field. The geographic coordinate system to which the defined projection applies must always be described.
- A.4.3.2.3 <u>DIG</u>. A relative coordinate system is the natural occurrence when using a digitising tool, a scanner, or raw imagery. These relative coordinate systems must be registered to an absolute coordinate system in order to represent real locations. The absolute coordinate systems may be GEO or MAP as described above. The registration between the relative and absolute coordinate systems will be defined either by the description of registration points (generally three or more) or by the description of location grid(s) (at least one). Normally, the error introduced during digitizing is small compared to the error in the source graphic, but it should not be ignored.
- A.4.3.3 Rectified image/raster local coordinate system. Rows and columns of a rectified image/raster data form a regular grid whose axes are parallel to the axes of the absolute coordinate system as defined in the GEOPS extension. When terrain relief is included in the rectification process, the result is called « ortho-rectified ». This will be more spatially correct, especially in area that have considerable elevation differences. In this local coordinate system, coordinate sets are composed of a row number and a column number (r,c). The order in which rows and columns are numbered is described in annex C paragraph 17. The GEOLO and MAPLO extensions provide the appropriate parameters for computing the spatial location of each pixel from its row and column number.
 - a. MAPLO must be used if the absolute coordinate system is a cartographic coordinate system (E, N). It defines the Easting and Northing of the origin of the grid (LSO,PSO) and the rows and columns width (LOD,LAD) using a defined linear unit (UNILOA).

$$E = LSO + c * LOD* (1_{UNI} / 1_{UNILOA})$$

$$N = PSO - r * LAD* (1_{UNI} / 1_{UNILOA})$$

NOTE: $(1_{UNI} / 1_{UNILOA})$ means the conversion of the unit of LOD (LAD) given by the field UNILOA into the unit of E (S) called UNI in these formulas. If the units are the same, this ratio is equal to 1.

b. GEOLO must be used if the absolute coordinate system is a geographic coordinate system (Long, Lat). It defines the longitude and latitude of the origin of the grid (LSO,PSO), and the number of rows and columns in 360° (ARV,BRV).

NB : $(360^\circ)_{UNI}$ means the value of a 360° angle expressed in the unit of Lat (Long). If the units are degrees, the value is 360.

A.4.3.4 <u>GRID reference image</u>. Non-rectified image or matrix data can be accurately geo-referenced with a grid reference image file. This is the GRDPS extension. Basically, this involves superimposing a grid of spatial location information on top of the image for which the spatial information applies. For example, the grid could have location information (coordinates) at every 10th image pixel (N-S) and (E-W). Then for every image pixel, one could interpolate, using surrounding grid pixels, to estimate the actual geospatial location. This scheme eliminates the need to re-sample the base image to place it in a rectified form. This is important if the base image was a map scanned at a relatively low resolution (e.g., 100 dots per inch) and the re-sampling process would tend to make the resultant raster map too blurred to read. This process also allows a very non-linear stretch within the image space to be geo-referenced with reasonable accuracy, for example, aircraft reconnaissance using low scan angles. This results in near field pixels relatively close together and far field pixels far apart. Even with a horizon in the image, one can fill pixel spaces above this horizon with null values to signal that spatial location has no meaning in this empty part of the scene. Another advantage of the grid reference is the simplification of the application software. By using the same grid reference scheme for various types of imagery, the application software can use the same logic and not require a library of algorithms for various projection and sensor parameter solutions.

The extension includes the file identifier (BAD = IID of the grid subfile) of the grid image subfile and precise coordinates of four bounding corners. The Grid Image ID can be found in the Image Subheader, Image ID (IID) field. It also contains the absolute elevation of the grid relative to mean sea level (WGS84). The elevation data provides spatial data refinement in areas where terrain relief complicates the geospatial reference problem. For regions of pronounced differences in terrain elevation, it may be necessary to include several sets of grid reference images where the elevation of the grid is adjusted to best match the terrain elevation over that region.

It is important to note that while the grid reference generally gives good accuracy, the quantitative accuracy value at each pixel is difficult to describe.

The grid image subfile is a NITF subimage containing two bands: Band X giving the longitude or easting coordinates and Band Y giving the latitude or northing coordinates for each grid element. The Band X image file field "ISUBCAT1" may be CGX or GGX and Band Y image file field "ISUBCAT2" may be CGY or GGY. CGX and CGY indicate geographic coordinates (latitude / longitude) and GGX and GGY indicate grid (easting (x) / northing (y)) coordinates.

Let (LSO, PSO) be the origin of the location grid in columns and rows within the image, (LOD, LAD) the interval (measured in image pixels) between 2 consecutive elements of grid (in columns, rows), also being the ratio of image pixels to grid pixels, by column and row.

Let (c,r) be the column and row numbers, of a pixel of interest, within the image. The location of the pixel (c,r) can be interpolated from the four grid points that surround it. Let (LGC, LGR) be the column and row number (in grid numbers) of the upper left corner of the grid square that surrounds the image pixel of interest. These values can be computed as follows:

$$LGC = [(c-LSO) / LOD]$$

$$LGR = [(r-PSO) / LAD]$$

$$where... [x] = integer part of x$$

Let the four corners of the grid square be numbered 1, 2, 3, 4, as shown on figure A-1. The upper left corner (corner number 1) column and row indexes are $(C_1, R_1) = (LGC, LGR)$. The column and row numbers (C_i, R_i) , (i = 2, 3, 4) of the other corners are:

$$(C_2, R_2) = (LGC+1, LGR), (C_3, R_3) = (LGC, LGR+1), (C_4, R_4) = (LGC+1, LGR+1).$$

For the example in figure A-1 the solutions are:

$$(C_1, R_1) = (1,0)$$
 $(C_2, R_2) = (2,0)$ $(C_3, R_3) = (1,1)$ $(C_4, R_4) = (2,1)$

The image pixel coordinates of the 4 grid corners (c_i, r_i) , (i = 1,2,3,4) can be computed as:

$$(c_i, r_i) = (LSO + C_i * LOD, PSO + R_i * LAD).$$

For the example the solutions are:

$$(c_1, r_1) = (5,3)$$

$$(c_2, r_2) = (8,3)$$

$$(c_3, r_3) = (5,7)$$

$$(c_4, r_4) = (8,7)$$

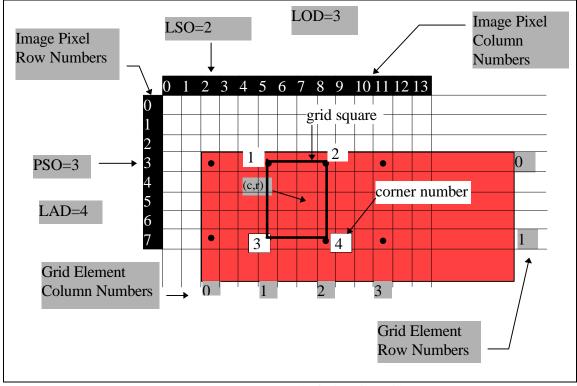


FIGURE A-1. Example of a location grid.

In this example, the pixel of interest is (c, r) = (7, 5).

The location information provided by grid data at each of the four corners (X_i, Y_i) , (i = 1,2,3,4) is given by: $(X_i, Y_i) = (BandX(C_i, R_i), BandY(C_i, R_i))$.

The interpolation algorithm is a bilinear interpolation between the 4 corners of the grid square. The column and row deltas (a and b), for c and r, are computed as follows:

$$a = (c - c_1) / LOD = (c - (LSO + C_1 * LOD)) / LOD$$

 $b = (r - r_1) / LAD = (r - (PSO + R_1 * LAD)) / LAD$

and a and b lie between 0 and 1.

The location (X,Y) of the pixel (c,r) is then given by :

$$X = (1-a) * (1-b) * X_1 + a * (1-b) X_2 + (1-a) * b * X_3 + a * b * X_4$$

 $Y = (1-a) * (1-b) * Y_1 + a * (1-b) Y_2 + (1-a) * b * Y_3 + a * b * Y_4$

For the example, the values of (a and b) are:

$$a = (c - c_1) / LOD = (7 - 5) / 3 = 2/3 \ and \qquad b = (r - r_1) / LAD = (5 - 3) / 4 = 1/2$$
 giving the interpolation algorithm the following weighted sum:

$$X = X_1/6 + X_2/3 + X_3/6 + X_4/3$$

 $Y = Y_1 /6 + Y_2/3 + Y_3/6 + Y_4/3$

Note that the sum of the weights (1/6 + 1/3 + 1/6 + 1/3) is always equal to 1.

The coding of bands values BandX and BandY will be:

- either integer for cartographic grids, giving easting and northing (in meters); in that case, the values of fields of sub-image header file or location grid data are:

$$PVTYPE = INT, NBANDS = 2,$$
 $IREPBAND1 = LX, ISUBCAT1 = CGX,$ $IREPBAND2 = LY, ISUBCAT2 = CGY.$

- or real (float) for geographic grids, giving longitude and latitude (in decimal seconds); in that case, the values of fields of sub-image header file or location grid data are:

$$PVTYPE = R, NBANDS = 2, \\ IREPBAND1 = LX, ISUBCAT1 = GGX, \\ IREPBAND2 = LY, ISUBCAT2 = GGY.$$

Grid and elevation (applies to imagery - not applicable to raster maps)

A grid is computed at a given elevation, and is valid for that elevation. In most cases, the location given by a grid varies smoothly with this elevation.

If the surface covered by the image is flat, its associated grid should be computed at the average ground elevation in this area.

Otherwise in case of significant elevation variations over the spot covered by the grid, the image is associated with two grids, one at minimum elevation \mathbf{z}_{min} , and the other at maximum elevation \mathbf{z}_{max} . A more accurate location of the pixel of interest can be computed by a linear interpolation between the locations computed with the two grids taking account of the estimated elevation from some additional data (such as digital terrain model or maps).

The process is then the following:

- computing the location with the two grids : $(X_{\text{min}}$, $Y_{\text{min}})$ at elevation z_{min} , $(X_{\text{max}}$, $Y_{\text{max}})$ at elevation z_{max} .
- from an additional data (e.g Digital Terrain Model, map ...), estimation of elevation \mathbf{z} of pixel (whose location can be estimated as $((X_{min} + X_{max})/2, (Y_{min} + Y_{max})/2)$.
- compute : $\mu = (z z_{min}) / (z_{max} z_{min})$ (notice that $0 \le \mu \le 1$).
- compute the final location (X, Y) by linear interpolation :

$$(X,\,Y) = ((1\text{-}\mu)\;X_{min} + \mu\;X_{max}\;,\,(1\text{-}\mu)\;Y_{min} + \mu\;Y_{max})$$

This solution is robust only when the elevation gradient is smooth.

- A.4.3.5 <u>Registration points</u>. Each registration point is described by two sets of coordinates: one describes the position of the point using the absolute coordinate system (as described in the GEOPS extension), the other describes the position of the same point in the relative coordinate system (as used in the data set). The REGPT extension is used to support relative coordinate systems. Note: The position accuracy will be affected by the mathematical function used to transform the coordinates from the relative coordinate system to the absolute one. This process is often referred to a "rubber sheeting" or "warping" an image (or scanned raster file) to best fit an absolute coordinate system. The mathematics will obviously be improved if approximate pixel spacing (in terms of the absolute coordinate system) is known.
- A.4.3.6 <u>Geo-reference values for certain standard products</u>. Several standard raster map products exist for which the geo-reference values are understood by default. These default values are summarised in this section:
 - * Arc Standard Raster Products (ASRP)

Type Geographic (GEO)
Units Seconds (SEC)

Ellipsoid WGS84 Datum WGS84

Projection ARC (using Zone Number supplied in GEOLO)

* UTM/UPS Standard Raster Products (USRP)

Type Cartographic (MAP)

Units Meters (M) Ellipsoid WGS84 Datum WGS84

If Zone Number is +60 to +1 (for north of Equator) or -60 to -1 (for south of Equator) the default projection will be:

Projection Universe Transverse Mercator

Parameter 1 Central Meridian for UTM Zone (Given in MAPLO)

Parameter 2 0.9996 Parameter 3 None Parameter 4 None

X(Easting) false origin of projection 500000

Y(Northing) false origin of projection 0(N) or 10000000(S)

consistent with Zone Number given in MAPLO Extension

If Zone Number is + 61 or -61 the default projection will be:

Projection Universal Polar Stereographic

Parameter 1 0 or 648000 Parameter 2 0.994 Parameter 3 None Parameter 4 None

X(Easting) false origin of projection 2000000 Y(Northing) false origin of projection 2000000

- A.4.4 Positional accuracy. Positional accuracy is expressed as a circular error for X,Y-value and as linear error for Z-value according to STANAG 2215.
- A.4.4.1 Horizontal and vertical accuracy regions. There must be 100% areal coverage of the georeferenced image item extent for the total area of the horizontal accuracy regions and 100% areal coverage of the geo-referenced image item extent for the sum of the vertical accuracy regions. Where the information is unknown or not applicable it will be noted with "Not a Number" value. Where the region or sub-region boundaries are coincident with both horizontal and vertical accuracy regions, then the accuracy regions may be combined in the same accuracy support data extension ACCPO. Where the horizontal and vertical boundaries differ in whole or in part, then either totally distinct horizontal and vertical sub-regions may be defined (ACCHZ, ACCVT), or the two approaches may be mixed (e.g., figure A-1).

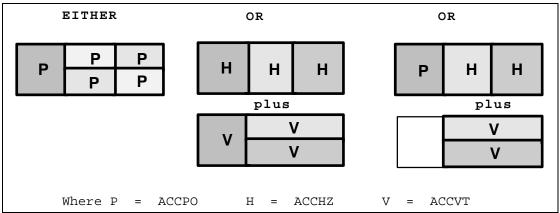


FIGURE A-2. Alternatives for defining mixed positional accuracy areas.

A.5 DETAILED REQUIREMENTS

NUM PRJ

A.5.1. <u>GEOPS - Geo positioning information</u>. GEOPS defines the absolute coordinate system to which the data is geo-referenced. This absolute coordinate system may be a geographic system or a cartographic coordinate system. The GEOPS extension is detailed in table A-1. A single GEOPS must be placed in the Image Subheader Extended Subheader Data field for each geo-referenced image item in a NITF file.

TABLE A-1. <u>GEOPS - Geo positioning information extension</u>. (TYPE "R" = Required "C" = Conditional)

	(111L R - Required C - Conditional)					
FIELD	NAME	SIZE	VALUE RANGE	TYPE		
CETAG	Unique Extension Identifier.	5	BCS-A	R		
			GEOPS			
CEVER	Version.	1	BCS-A	R		
			A			
CEL	Length of Data to Follow (e.g., length of	5	BCS-N	R		
	data in tag data field).		151+ NUM_PRJ *15+ 30			
The following f	ields define GEOPS					
TYP	Type of Coordinate System. Type of	3	BCS-A	R		
	Coordinate system for the image data:		MAP, GEO, or DIG			
	GEO: longitude, latitude; MAP: Easting,					
	Northing; DIG longitude, latitude or					
	Easting, Northing registered through a					
	location grid or registration points					
UNI	Units of Measure for Coordinates. Units	3	BCS-A	R		
	of measure for this data set.		See Table G-1			

	Easting, Troiting registered anough a			
	location grid or registration points			
UNI	Units of Measure for Coordinates. Units	3	BCS-A	R
	of measure for this data set.		See Table G-1	
ELL	Ellipsoid Name. Name of the ellipsoid to	25	BCS-A	R
	which the Data set refers. (See DIGEST		See Table G-1	
	1.2 Part 3 - 10)			
ELC	Ellipsoid Code. Code of the ellipsoid to	3	BCS-A	R
	which the Data set refers.		See Table G-1	
DVR	Vertical Datum Name.	25	BCS-A	R
			See Table F-3	
VDCDVR	Vertical Datum Code.	4	BCS-A	R
			See Table F-3	
DAG	Datum Geodetic Name.	25	BCS-A	R
			See Table F-2	
DCD	Datum Geodetic Code.	4	BCS-A	R
			See Table F-2	
GRD	Cartographic Grid Code Code of the	3	BCS-A	R
	Grid system. Defaulted to blank spaces.		(See Table F-6)	
GRN	Grid Description Text description of the	25	BCS-A	R
	Grid system. Defaulted to blank spaces			
ZNA	Grid Zone number Necessary when the	3	BCS-N	R
	Grid System comprise more than one			
	zone. Defaulted to 000 otherwise.			
PRN	Projection Name.	25	BCS-A	R
			See Table F-5	
PCO	Projection Code.	2	BCS-A	R

1

Number of Projection Parameters

See Table F-5

BCS-N 0-9 R

 $\frac{\text{TABLE A-1.}}{(\text{TYPE "R"} = \text{Required "C"} = \text{Conditional})} \text{- Continued.}$

FIELD	NAME	SIZE	VALUE RANGE	TYPE				
For each project	For each projection parameter							
PRJ	Projection Parameter	15	BDS-N	С				
	(See Table F-5)		± ddd.ddddddddd /					
			± mmmmmmmmmm.m					
NOTE: The fo	llowing fields are not included in the repet	ition of fi	elds designated by NUM_PRJ.					
XOR	Projection False X (Easting) Origin.	15	BCS-A	R				
			See Table F-5					
YOR	Projection False Y (Northing)Origin.	15	BCS-A	R				
			See Table F-5					

A.5.2. GRDPS - Grid reference data. When the image, matrix, or raster data is not rectified, the geographic location of each pixel may be derived from a given set of location grids computed for a given elevation. The user defined fields of the GRDPS extension are detailed in table A-2. A single GRDPS is placed in the Image Subheader, following GEOPS.

 $\begin{array}{ll} TABLE\ A-2. & \underline{GRDPS\ -\ Grid\ reference\ data\ extensions}.\\ (TYPE\ ^{"}R"\ =\ Required\ ^{"}C"\ =\ Conditional) \end{array}$

FIELD	NAME	SIZE	VALUE RANGE	TYPE
CETAG	<u>Unique Extension Identifier</u> .	5	BCS-A GRDPS	R
CEVER	Version.	1	BCS-A A	R
CEL	Length of Data to Follow (e.g., length of data in tag data field)	5	BCS-N 2 + NUM_GRDS * 68	R
The following	fields define GRDPS			
NUM_GRDS	Number of Location Grids.	2	BCS-N 01-20	R
For each locati	on grid			
ZVL	Elevation of the Grid (Meters).	10	BCS-N ± zzzzzzzzz.	R
BAD	Identifier of the Grid Image ID File.	10	BCS-A	R
LOD	<u>Data Interval in image pixels</u> . (column wise), also being ratio of image pixels to grid elements	5	BCS-N 00001-99999	R
LAD	<u>Data Interval in image pixels</u> . (row wise), also being ratio of image pixels to grid elements	5	BCS-N 00001-99999	R
LSO	Column Number of the Origin of Location Grid.	11	BCS-N	R
PSO	Row Number of the Origin of Location Grid.	11	BCS-N	R
NCOLS	Number of Columns in the Location Grid.	8	BCS-N 00000001-999999999	R
NROWS	Number of Rows in the Location Grid.	8	BCS-N 00000001-999999999	R

A.5.3 <u>GEOLO - Local geographic (lat/long) coordinate system</u>. For rectified data (rows and columns are aligned with the coordinate system axis) GEOLO provides the description of the link between the local coordinate system (rows and columns) and the absolute geographic coordinate system (longitude and latitude). The user defined fields of the GEOLO extension are detailed in table A-3. A single GEOLO is placed in the Image Subheader, following GEOPS.

 $\frac{\text{GEOLO - local geographic coordinate system extension.}}{(\text{TYPE "R"} = \text{Required "C"} = \text{Conditional})}$

	(TITE IV – Required C – Conditional)					
FIELD	NAME	SIZE	VALUE RANGE	TYPE		
CETAG	Unique Extension Identifier.	5	BCS-A	R		
			GEOLO			
CEVER	Version.	1	BCS-A	R		
			A			
CEL	Length of Data to Follow (e.g., length of data in	5	BCS-N	R		
	tag data field).		00048			
The following	fields define GEOLO					
ARV	Number of Elements in 360 Degrees (E-W).	9	BCS-N	R		
	Pixel ground spacingnumber of pixels in 360		000000002 -			
	degrees (E-W)		999999999			

Pixel ground spacingnumber of pixels in 360		000000002 -	
degrees (E-W)		99999999	
Number of Elements in 360 Degrees (N-S).	9	BCS-N	R
Pixel ground spacingnumber of pixels in 360		000000002 -	
degrees (N-S)		999999999	
Longitude of Reference Origin.	15	BCS-N	R
		\pm ddd.dddddddd	
Latitude of Reference Origin.	15	BCS-N	R
		\pm 0dd.dddddddd	
	degrees (E-W) Number of Elements in 360 Degrees (N-S). Pixel ground spacingnumber of pixels in 360 degrees (N-S) Longitude of Reference Origin.	degrees (E-W) Number of Elements in 360 Degrees (N-S). Pixel ground spacingnumber of pixels in 360 degrees (N-S) Longitude of Reference Origin. 15	degrees (E-W) Number of Elements in 360 Degrees (N-S). Pixel ground spacingnumber of pixels in 360 degrees (N-S) Longitude of Reference Origin. Latitude of Reference Origin. 15 BCS-N ± ddd.dddddddddddddddddddddddddddddddd

A.5.4 MAPLO - Local cartographic (x, y) coordinate system. For rectified data (rows and columns are aligned with the coordinate system axis) MAPLO provides the description of the link between the local coordinate system (rows and columns) and the absolute cartographic coordinate system (Easting and Northing). The user defined fields of the MAPLO extension are detailed in table A-4. A single MAPLO is placed in the Image Subheader, following GEOPS.

TABLE A-4. MAPLO - local cartographic coordinate system extension.

(TYPE "R" = Required "C" = Conditional)						
FIELD	NAME	SIZE	VALUE RANGE	TYPE		
CETAG	Unique Extension Identifier.	5	BCS-A	R		
	_		MAPLO			
CEVER	Version.	1	BCS-A	R		
			A			
CEL	Length of Data to Follow (e.g., length of	5	BCS-N	R		
	data in tag data field).		00043			
The following	fields define MAPLO					
LOD	Data Density for E/W Direction. Data	5	BCS-N	R		
	interval in E-W direction		00001-99999			
LAD	Data Density for N/S Direction. Data	5	00001-99999	R		
	interval in N-S direction					
UNILOA	Units of Measurement of LOD and LAD.	3	BCS-A	R		
			See Table G-1			

TABLE A-4. MAPLO - local cartographic coordinate system extension - Continued.

FIELD	NAME	SIZE	VALUE RANGE	TYPE
LSO	Easting of Reference Origin.	15	BCS-N	R
			± mmmmmmmmmm.m	
PSO	Northing of Reference Origin.	15	BCS-N	R
			± mmmmmmmmmm.m	

A.5.5 <u>REGPT - Registration points</u>. Registration points may be provided for image or map data to identify specific pixels in this data and provide spatial locations (geographic or cartographic) for these pixels. With this information the entire image or map pixel set can be adjusted to improve overall accuracy. The extension is called REGPT and table A-5 details the user defined fields.

 $\begin{array}{ll} TABLE\ A-5. & \underline{REGPT\ -\ Registration\ point\ extension}. \\ (TYPE\ "R"\ =\ Required\ "C"\ =\ Conditional) \end{array}$

FIELD	NAME	SIZE	VALUE RANGE	TYPE
CETAG	Unique Extension Identifier.	5	BCS-A	R
			REGPT	
CEVER	Version.	1	BCS-A	R
			A	
CEL	Length of Data to follow (e.g., length of	5	(BCS_N)	R
	data in tag data field).		2 + NUM_PTS * 83	
The following	g fields define REGPT			
NUM_PTS	Number of Registration Points to	2	BCS-N	R
	Follow.		01 - 99	
For each regi	stration point	•	•	•
PID	Point Identification.	5	BCS-A	R
LONG	Longitude/Easting of Registration Point.	15	BCS-N	R
			± ddd.dddddd /	
			± mmmmmmmmmm.m	
LAT	Latitude/Northing of Registration Point.	15	BCS-N	R
			± 0dd.dddddd /	
			± mmmmmmmmmm.m	
ZVL	Elevation of Registration Point.	15	BCS-N	R
			± mmmmmmmmmm.m	
DIX	Column Number of Registration Point.	11	BCS-N	R
			0000000001-	
			9999999999	
DIY	Row Number of Registration Point.	11	BCS-N	R
			0000000001-	
			9999999999	
DIZ	Local Z Coordinate of Registration	11	BCS-N	R
	Point.		± mmmmmmm.m	

 $A.5.6 \ \ \, \underline{ACCPO\ -\ Positional\ accuracy}. \ \ \, The\ user\ defined\ fields\ of\ the\ ACCPO\ extension\ are\ detailed\ in\ table\ A-6.\ \ \, If\ horizontal\ (ACCHZ)\ and\ vertical\ (ACCVT)\ extensions\ are\ used\ then\ ACCPO\ will\ not\ be\ used.$

TABLE A-6. <u>ACCPO - Positional accuracy extension</u>. (TYPE "R" = Required "C" = Conditional)

	(TYPE "R" = Required "C" = C	conditional)		
FIELD	NAME	SIZE	VALUE RANGE	TYPE
CETAG	Unique Extension Identifier.	5	BCS-A	R
			ACCPO	
CEVER	Version.	1	BCS-A	R
			A	
CEL	Length of Data to Follow (e.g., length of data	5	BCS-N	R
	in tag data field).		2 + NUM_ACPO * (34	
			+ NUM_COO*30)	
The following	fields define ACCPO			I
NUM_ACPO	Number of ACCPO Record Sets to Follow.	2	BCS-N	R
110111_11010	This field defines the number of accuracy sets	~	01 - 20	10
	to follow. The number will be "01" if the		01 20	
	entire data set only has one set of accuracy. If			
	vertical and horizontal accuracy are not			
	homogeneous within definable regions then			
	there may be different numbers of sets between			
	horizontal and vertical. The maximum number			
	of regions is limited to 20.			
	PO record (defined by the following fields of AC	1		
AAH	Absolute Horizontal Accuracy. Absolute	5	BCS-N	R
	horizontal accuracy for the defined region/sub-		00000-99999	
	region			
UNIAAH	<u>Unit of Measure for AAH</u> . Units for AAH (See	3	BCS-A	R
	Table G-1)			
AAV	Absolute Vertical Accuracy. Absolute vertical	5	BCS-N	R
	accuracy for the defined region/sub-region		00000-99999	
UNIAAV	Unit of Measure for AAV. Units for AAV (See	3	BCS-A	R
	Table G-1)			
APH	Point-to-Point (Relative) Horizontal. Point-to-	5	BCS-N	R
	point (relative) horizontal accuracy for the		00000-99999	10
	defined region/sub-region		00000 33333	
UNIAPH	Unit of Measure for APH. Units for APH (See	3	BCS-A	R
UNIAFII	Table G-1)	3	BC3-A	I.
APV	,	5	BCS-N	R
APV	Point-to-Point (Relative) Vertical. Point-to-)		K
	point (relative) vertical accuracy for the defined		00000-99999	
TINITA DI 7	region/sub-region		D.C.C. A	
UNIAPV	Unit of Measure for APV. Units for APV (See	3	BCS-A	R
	Table G-1)			_
NUM_COO	Number of Coordinates in Bounding Polygon.	2	BCS-N	R
	This field defined the number of coordinate	1	00-20	
	pairs that are used to define a sub-region. If the	1		
	accuracy information applies to the entire data	1		
	set, then this field does not apply and will be	1		
	zero filled.	1		
	1	1	ı	1

TABLE A-6. ACCPO - Positional accuracy extension - Continued.

FIELD	NAME		SIZE	VALUE RANGE	TYPE	
For each coord	For each coordinate pair (the following 2 fields only appear when NUM_COO is not 00)					
LONG	Longitude(DEG)/Easting (M). Longitude	15	BCS-	·N	С	
	or Easting coordinate value (Longitude in		$\pm ddc$	d.ddddddddd /		
	decimal degrees and Easting in meters).		± mn	nmmmmmmmm.m		
LAT	Latitude (DEG)/Northing(M). Latitude or	15	BCS-	·N	С	
	Northing coordinate value (Latitude in		$\pm 0 dc$	d.ddddddddd /		
	decimal degrees and Northing in meters).		± mn	nmmmmmmmm.m		

Note 1 : Accuracy values are computed as 90% probable (ref. STANAG 2250).

Note 2 : The coordinate system (Latitude/Longitude or Northing/Easting) is defined in the GEOPS extension.

A.5.7 ACCHZ - Horizontal accuracy. The user defined fields of the ACCHZ extension are detailed in table A-7.

 $\begin{array}{c} TABLE\ A-7. \\ \hline (TYPE\ "R" = Required\ "C" = Conditional) \end{array} .$

FIELD	NAME	SIZE	VALUE RANGE	TYPE
CETAG	Unique Extension Identifier.	5	BCS-A	R
			ACCHZ	
CEVER	Version.	1	BCS-A	R
			A	
CEL	Length of Data to Follow (e.g., length of	5	BCS-N	R
	data in tag data field).		2 + NUM_ACHZ *	
			$(18 + NUM_COO*30)$	

The following fields define ACCHZ...

NUM_ACHZ	Number of ACCHZ Record Sets to	2	BCS-N	R
	Follow. This field defines the number of		01 - 20	
	accuracy sets to follow. The number will			
	be "01" if the entire data set only has one			
	set of accuracy. If vertical and horizontal			
	accuracy are not homogeneous within			
	definable regions then there may be			
	different numbers of sets between			
	horizontal and vertical. The maximum			
	number of regions is limited to 20.			

For each ACCHZ record... (defined by the following fields of ACCHZ extension)

AAH	Absolute Horizontal Accuracy. Absolute	5	BCS-N	R
	horizontal accuracy for the defined		00000-99999	
	region/sub-region			
UNIAAH	Unit of Measure for AAH. Units for AAH	3	BCS-A	R
	(See Table G-1)			
APH	Point-to-point (Relative) Horizontal.	5	BCS-N	R
	Point-to-point (relative) horizontal		00000-99999	
	accuracy for the defined region/sub-region			
UNIAPH	<u>Unit of Measure for APH</u> . Units for APH	3	BCS-A	R
	(See Table G-1)			

TABLE A-7. ACCHZ - Horizontal extension - Continued.

FIELD	NAME	SIZE	VALUE RANGE	TYPE
NUM_COO	Number of Coordinates in Bounding	2	BCS-N	R
	Polygon. This field defined the number of		00-20	
	coordinate pairs that are used to define a			
	sub-region. If the accuracy information			
	applies to the entire data set, then this field			
	does not apply and will be zero filled.			
For each coordi	inate pair (the following 2 fields only appear	when NU	JM_COO is not 00)	
LONG	Longitude(DEG)/Easting (M). Longitude	15	BCS-N	C
	or Easting coordinate value (Longitude in		± ddd.dddddddd /	
	decimal degrees and Easting in meters).		± mmmmmmmmmm.m	
LAT	Latitude (DEG)/Northing (M). Latitude or	15	BCS-N	C
	Northing coordinate value (Latitude in		± 0dd.ddddddddd /	
	decimal degrees and Northing in meters).		± mmmmmmmmmm.m	

decimal degrees and Northing in meters). \pm mmr Note 1 : Accuracy values are computed as 90% probable (ref. STANAG 2250).

Note 2: The coordinate system (Latitude/Longitude or Northing/Easting) is defined in the GEOPS extension.

A.5.8 $\,$ ACCVT - Vertical accuracy. The user defined fields of the ACCVT extension are detailed in table A-8.

 $\begin{array}{ll} TABLE\ A-8. & \underline{ACCVT\ -\ Vertical\ accuracy\ extension}.\\ (TYPE\ "R"\ =\ Required\ "C"\ =\ Conditional) \end{array}.$

	(1) PE R = Required C			
FIELD	NAME	SIZE	VALUE RANGE	TYPE
CETAG	Unique Extension Identifier.	5	BCS-A	R
			ACCVT	
CEVER	Version.	1	BCS-A	R
			A	
CEL	Length of Data to Follow (e.g., length of	5	BCS-N	R
	data in tag data field).		2 + NUM_ACVT *	
			$(18 + NUM_{COO}*30)$	
The following f	ields define ACCVT			•
NUM_ACVT	Number of ACCVT Record Sets to	2	BCS-N	R
	Follow. This field defines the number of		01 - 20	
	$\overline{\text{accuracy}}$ sets to follow. The number will			
	be "01" if the entire data set only has one			
	set of accuracy. If vertical and			
	horizontal accuracy are not homogeneous			
	within definable regions then there may			
	be different numbers of sets between			
	horizontal and vertical. The maximum			
	number of regions is limited to 20.			
For each ACCV	T record (defined by the following fields	of ACCV	T extension)	
AAV	Absolute Vertical Accuracy. Absolute	5	BCS-N	R
	vertical accuracy for the defined		00000-99999	
	region/sub-region			
UNIAAV	Unit of Measure for AAV. Units for	3	BCS-A	R
	AAV (See Table G-1)			
	1117 (000 14010 0 1)		1	1

TABLE A-8. ACCVT - Vertical accuracy extension - Continued.

FIELD	NAME	SIZE	VALUE RANGE	TYPE
APV	Point-to-Point (Relative) Vertical. Point-to-point (relative) vertical accuracy for the defined region/sub-region	5	BCS-N 00000-99999	R
UNIAPV	Unit of Measure for APV. Units for APV (See Table G-1)	3	BCS-A	R
NUM_COO	Number of Coordinates in Bounding Polygon. This field defined the number of coordinate pairs that are used to define a sub-region. If the accuracy information applies to the entire data set, then this field does not apply and will be zero filled.	2	BCS-N 00-20	R
For each coord	inate pair (the following 2 fields only appear	ar when N	NUM_COO is not 00)	
LONG	Longitude (DEG)/Easting (M). Longitude or Easting coordinate value (Longitude in decimal degrees and Easting in meters).	15	BCS-N ± ddd.dddddddddd / ± mmmmmmmmmmm.m	С
LAT	Latitude (DEG)/Northing (M). Latitude or Northing coordinate value (Latitude in decimal degrees and Northing in meters).	15	BCS-N ± 0dd.dddddddddd / ± mmmmmmmmmmm.m	С

Note 1 : Accuracy values are computed as 90% probable (ref. STANAG 2250).

Note 2: The coordinate system (Latitude/Longitude or Northing/Easting) is defined in the GEOPS extension.

APPENDIX B

MAP SOURCE DATA EXTENSION

B.1 SCOPE

The map source data extension (SOURC) provides extensive information about the source graphics (one or more). Since these sources are maps or charts, a cartographic (MAP) coordinate system applies and must include ellipsoid, datum, and projection data. In addition, if elevation or depth information is present on the source map, the vertical or sounding datum must be supplied.

B.2 APPLICABLE DOCUMENTS

The applicable documents in section 2 MIL-STD-2500B apply to this appendix.

B.3 DEFINITIONS

The definitions in section 3 MIL-STD-2500B apply to this appendix.

B.4 GENERAL REQUIREMENTS

The source graphic may include several map insets and usually includes legend data that is important to capture as raster files. Insets have a specific coordinate system defined which may be different for each one and different than the one used for the main source graphic. The mechanism is the same as for relative coordinate systems with the four corners of the inset interpreted as registration points. Relative coordinates give the location of the outside of the corners (as computed from the row and column number of each corner). Absolute coordinates will give the location of the inside of the corners. Both locations will be described in the same coordinate system as defined in the GEOPS extension. The only transformation allowed is change of scale and offset.

In northern latitudes, certain maps may include a grid overlay for convenience of navigation where longitude arcs are rapidly converging. The overlays normally include Grid North-Magnetic North Angle (GMA) and a Grid Convergence Angle (GCA). Note: When the primary grid displayed on the map is not strictly registered to the map projection, it is best to use the projection to which the primary grid is registered to the map projection. This allows the application to use the parameters of the source file for transforming the coordinates from the coordinate system of the data set to the coordinate system displayed on the grid.

B.5 DETAILED REQUIREMENTS

 $B.5.1\ \, \underline{SOURC\ -\ Map\ source\ description}. \ \, The\ user\ defined\ fields\ of\ the\ SOURC\ extension\ are\ detailed\ in\ table\ B-1,\ and\ the\ descriptions\ of\ these\ fields\ are\ detailed\ in\ table\ B-2.$

TABLE B-1. SOURC - Source extension.

(TYPE "R" = Required "C" = Conditional)

ME SIZE

FIELD	(TYPE "R" = Require NAME	SIZE	VALUE RANGE	TYPE
CETAG	Unique Extension Identifier.	5	BCS-A	R
			SOURC	
CEVER	Version.	1	BCS-A	R
			A	
CEL	Length of Data to Follow (e.g., length of	5	BCS-N	R
	data in tag data field).		2 +	
			NUM_SOUR *	
			$(312 + NUM_MAG * 74 + 2)$	
			+ NUM_COO *30 + 28 +	
			NUM_PRJ*15 + 90+ NIN *284	
TD1 C 11	. C. I. I. C. COLIDO		+ NLI *27)	
	ring fields define SOURC	1.0	I DOG N	
NUM_S	Number of Source Description	2	BCS-N	R
OUR				
For each se		10	DCC A	R
BAD	Identifier of Derived Image layer	10	BCS-A	K
NLI	(Image ID) Number of Legend Images	2	BCS-N	R
NIN	Number of Legend Images Number of Insets	2	BCS-N	R
PRT	Series Designator	10	BCS-A	R
1101	Series Designator	10	(e.g. 1501G)	IC.
URF	Unique Source ID	20	BCS-A	R
CKI	(Number or name which, when used	20	BOS A	10
	with series and edition, will uniquely			
	identify the source)			
EDN	Source Edition Number	7	BCS-A	R
NAM	Full Name of Source Document	20	BCS-A	R
CDP	Type of Significant Date	3	BCS-N	R
	(that most accurately describes basic		(See Table E-1)	
	date of the product for computation of			
	the probable obsolescence date. It can			
	be compilation date, revision date, or			
	other depending on the product and			
	circumstances.)			
CDV	Significant Date Value	8	BCS-A (YYYYMMDD)	R
CDV27	Perishable Information Date Value	8	BCS-A (YYYYMMDD)	R
SCA	Reciprocal Cartographic Scale	9	BCS-N	R
GRD	Cartographic Grid Code Code of the	3	BCS-A	R
	Grid system. Defaulted to blank		(See Table F-6)	
CDV	spaces.	0.5	DGG A	<u> </u>
GRN	Grid Description Text description of	25	BCS-A	R
	the Grid system. Defaulted to blank			
	spaces			

TABLE B-1. <u>SOURC - Source extension</u> - Continued.

FIELD	NAME	SIZE	VALUE RANGE	TYPE
ZNA	Grid Zone number Necessary when the	3	BCS-N	R
	Grid System comprise more than one			
	zone. Defaulted to 000 otherwise.			
SQU	Area Coverage	10	BCS-N	R
	(Number of square units in coverage)			
UNISQU	Unit of Measure for SQU	3	BCS-A	R
			(See Table F-1)	
PCI	Predominant Contour Interval	4	BCS-N	R
UNIPCI	Unit of Measure for Contour Interval	3	BCS-A	R
			(See Table F-1)	
WPC	Percentage Covered by Water	3	BCS-N	R
NST	Navigation System Type	3	BCS-N	R
			(See Table F-2)	
ELL	Ellipsoid Name to which the source	25	BCS-A	R
	refers		(See Table F-1)	
ELC	Ellipsoid Code	3	BCS-A	R
	-		(See Table F-1)	
DVR	Datum Vertical Reference	25	BCS-A	R
			(See Table F-3)	
VDCDV	Code for Datum of Vertical Reference	4	BCS-A	R
R			(See Table F-3)	
SDA	Sounding Datum Name	25	BCS-A	R
			(See Table F-4)	
VDCSDA	Code for Sounding Datum	4	BCS-A	R
	Ŭ.		(See Table F-4)	
DAG	Geodetic Datum Name	25	BCS-A	R
			(See Table F-2)	
DCD	Geodetic Datum Code	4	BCS-A	R
			(See Table F-2)	
HKE	Highest Known Elevation in Source	6	BCS-N	R
			$(e.g \pm NNNNN)$	
UNIHKE	Units of HKE	3	BCS-A	R
			(See Table G-1)	
LONG	Longitude/Easting of HKE	15	BCS-N	R
			± ddd.ddddddddd /	
			± mmmmmmmmmm.m	
LAT	Latitude/Northing of HKE	15	BCS-N	R
			± 0dd.ddddddddd /	
			± mmmmmmmmmm.m	
NUM_M	Number of Sets of Magnetic	2	BCS-N	R
AG	Information		00-20	
For each se	et of magnetic information (the following	fields only a	appear when NUM_MAG is not 0	0)
CDP	Type of Date	3	BCS-N	R
			(See Table E-1)	
CDV	Date of Magnetic Information	8	BCS-A	R
	0		(YYYMMDD)	
RAT	Annual Angular Magnetic Rate of	8	BCS-N	R
	Change			
	(actual real value)			

TABLE B-1. <u>SOURC - Source extension</u> - Continued.

FIELD	NAME	SIZE	VALUE RANGE	TYPE
UNIRAT	Units for Magnetic Rate of Change	3	BCS-A	R
OTVIIC/TI	Onto for Magnetic Rate of Change		(See Table G-1)	10
GMA	Grid North - Magnetic North Angle	8	BCS-N	R
diviA	(GMA)	0	DCS IV	IV.
UNIGMA	Units of GMA	3	BCS-A	R
UNIGNIA	Ollis of GiviA	3	(See Table G-1)	I IC
LONG	Longitude/Easting Coordinate of GMA	15	BCS-N	R
LONG	Reference Point	13	± ddd.ddddddddd /	IK .
	Reference 1 out		± mmmmmmmmmmm.m	
LAT	Latitude/Northing Coordinate of GMA	15	BCS-N	R
LAI	Reference Point	13	± 0dd.ddddddddd /	IK .
	Reference 1 offit		± mmmmmmmmmmm.m	
GCA	Grid Convergence Angle	8	BCS-N	R
GCA	(actual real value)	0	DC3-IV	K
UNIGCA	Units of GCA	3	BCS-A	R
UNIGCA	Units of GCA	3	(See Table G-1)	K
NOTE T			,	
	he following fields are not included in the re	•		T D
NUM_C	Number of Coordinates in Bounding	2	BCS-N	R
00	Polygon		(04 - 99)	
	oordinate	1		
LONn	Longitude/Easting of Point	15	BCS-N	R
			± ddd.ddddddddd /	
			± mmmmmmmmmm.m	
LATn	Latitude/Northing of Point	15	BCS-N	R
			± 0dd.ddddddddd /	
			± mmmmmmmmmm.m	
NOTE: T	he following fields are not included in the re	epetition of	fields designated by NUM_COO.	
PRN	Projection Name	25	BCS-A	R
	, and the second		(See Table F-5)	
PCO	Projection Code	2	BCS-A	R
	, and the second		(See Table F-5)	
NUM_PRJ	Number of Projection Parameters	1	BCS-N	R
_	<u> </u>		0-9	
For each p	rojection parameter	1	•	
PR.J	Projection Parameter	15	BDS-N	С
. = - =	See Table F-5		± ddd.ddddddddd /	
			± mmmmmmmmmm.m	
	I	1		
NOTE: T	he following fields are not included in the re	netition of	fields designated by NIIM PRI	
XOR	X (Easting) False Origin of	15	BCS-N	R
21010	Projection		± mmmmmmmmmmm.	10
YOR	Y (Northing) False Origin of	15	BCS-N	R
IOI	Projection	10	± mmmmmmmmmmm.	10
220	Security Classification of Source	1		D
QSS		1	T S C R U	R
QOD	Originator's Permission Required for	1	Y N	R
CDV10	Downgrading (Y or N)	0	3/3/3/3/MADD	D
CDV10	Downgrading Date Value	8	YYYYMMDD (Blank if QODSS is "Y")	R

TABLE B-1. SOURC - Source extension - Continued.

NAME SIZE VALUE RANGE.

FIELD	NAME	SIZE	VALUE RANGE	TYPE
QLE	Releasibility	25	BCS-A	R
	(If no release restrictions exits,			
	"UNRESTRICTED" shall be			
	entered)			
CPY	Copyright Statement	25	BCS-A	R
	(If none, "UNCOPYRIGHTED"			
	shall be entered)			
	set (the following fields only appear who	en NIN is not		
INT	Unique ID for Inset	10	BCS-A	R
SCA	Reciprocal Scale of inset	9	BCS-N	R
NAM	Name of Inset	25	BCS-A	R
NTL	Absolute longitude of lower left	15	BCS-N	R
	corner of inset		± ddd.ddddddddd /	
			± mmmmmmmmmm.m	
TTL	Absolute latitude of lower left corner	15	BCS-N	R
			± 0dd.ddddddddd /	
			± mmmmmmmmmm.m	
NVL	Absolute longitude of upper left	15	BCS-N	R
	corner		± ddd.ddddddddd /	
			± mmmmmmmmmm.m	
TVL	Absolute latitude of upper left corner	15	BCS-N	R
			± 0dd.ddddddddd /	
			± mmmmmmmmmm.m	
NTR	Absolute longitude of upper right	15	BCS-N	R
	corner		± ddd.dddddddd /	
			± mmmmmmmmmm.m	
TTR	Absolute latitude of upper right	15	BCS-N	R
	corner		± 0dd.ddddddddd /	
			± mmmmmmmmmm.m	
NVR	Absolute longitude of lower right	15	BCS-N	R
	corner		± ddd.ddddddddd /	
			± mmmmmmmmmm.m	
TVR	Absolute latitude of lower right	15	BCS-N	R
	corner		± 0dd.ddddddddd /	
			± mmmmmmmmmm.m	
NRL	Relative longitude of lower left	15	BCS-N	R
	corner		± ddd.ddddddddd /	
			± mmmmmmmmmm.m	
TRL	Relative latitude of lower left corner	15	BCS-N	R
			± 0dd.ddddddddd /	
			± mmmmmmmmmm.m	
NSL	Relative longitude of upper left	15	BCS-N	R
	corner		± ddd.ddddddddd /	
			± mmmmmmmmmm.m	
TSL	Relative latitude of upper left corner	15	BCS-N	R
			± 0dd.ddddddddd /	
			± mmmmmmmmmm.m	

TABLE B-1. SOURC - Source extension - Continued.

FIELD	NAME	SIZE	VALUE RANGE	TYPE
NRR	Relative longitude of upper right	15	BCS-N	R
	corner		± ddd.ddddddddd /	
			± mmmmmmmmm.m	
TRR	Relative latitude of upper right corner	15	BCS-N	R
			± 0dd.ddddddddd /	
			± mmmmmmmmm.m	
NSR	Relative longitude of lower right	15	BCS-N	R
	corner		± ddd.ddddddddd /	
			± mmmmmmmmm.m	
TSR	Relative latitude of lower right corner	15	BCS-N	R
			± 0dd.ddddddddd /	
			± mmmmmmmmm.m	

For each legend... (the following fields only appear when NLI is not 00)

NAM	Legend name	25	BCS-A	R
BAD	Image file Identifier	2	BCS-N	R
	(Image ID)		00 - 99	

TABLE B-2. SOURC field descriptions.

	TABLE B-2. SOURC field descriptions.
FIELD	NAME VALUE DEFINITIONS
NUM_SETS	Number of sources
BAD	Name of derived layer (IID)
NLI	Number of legend images
NIN	Number of insets
PRT	Series designator (e.g., 1501G)
URF	Source ID - Number or name which, when used with series and edition, will uniquely identify
	the source
EDN	Source edition number
NAM	Full name of source document
CDP	Significance date that most accurately describes basic date of the product for computation of the
	probable obsolescence date. It can be compilation date, revision date, or other depending on
	the product and circumstances. (See DIGEST, Part 4, Annex B for date codes) (CDP)
CDV	Significant date value
CDV27	Perishable information date value
COU	Country code
SCA	Reciprocal of cartographic scale
GRD	Cartographic grid (See DIGEST part 3-7)
SQU	Number of square units (see below) in coverage
UNIsqu	Units of measure for SQU
PCI	Predominant contour interval
UNIpci	Units of measure for PCI
WPC	Percentage covered by water
NST	Navigation system type
ELL	Ellipsoid name to which the source refers
ELC	Ellipsoid code
DVR	Name of vertical reference
VDCdvr	Code of vertical datum
SDA	Name of sounding datum

 $TABLE\ B-2.\ \ \underline{SOURC\ field\ descriptions}\ -\ Continued.$

FIELD	NAME VALUE DEFINITIONS
VCDsda	Code of vertical datum for soundings
DAG	Name of geodetic datum
DCD	Code of geodetic datum
HKE	Highest known elevation on source
UNIhke	Units of measurement for HKE
LON	Longitude/Easting of highest elevation
LAT	
	Latitude/Northing of highest elevation
NUM_MAG	Number of sets of magnetic rate information
CDP	Smagnetic rate information
CDV	Type of magnetic rate information
	Date of magnetic rate information
RAT	Annual angular rate of change
UNIrat	Units of measurement for RAT
GMA	Grid North - Magnetic North Angle
UNIgma	Units of measurement for GMA
LON	Longitude/Easting of GMA reference point
LAT	Latitude/Northing of GMA reference point
GCA	Grid convergence angle
UNIgca	Units of measurement for GCA
NUM_COO	Number of coordinates in the bounding polygon for the source
	linate in the bounding polygon
LON	Longitude/Easting
LAT	Latitude/Northing
PRN	Name of the projection used in the source
PCO	Code for the projection
PAA	Projection parameter no. 1
PAB	Projection parameter no. 2
PAC	Projection parameter no. 3
PAE	Projection parameter no. 4
XOR	X (Easting) false origin of the projection
YOR	Y (Northing) false origin of the projection
QSS	Security classification of source
QOD	Originator's permission needed for downgrading ("Y" or "N")
CDV10	Date of downgrading (Blank if QSS is "Y")
QLE	Releasability restrictions. If no release restrictions exits, "UNRESTRICTED" shall be entered
'	in this entry.
CPY	Copyright statement. If none, "UNCOPYRIGHTED" shall be placed in this entry.
For each inset.	
INT	Unique ID for the inset
SCA	Reciprocal of cartographic scale of inset
NAM	Name of inset
NTL	Absolute longitude of lower left corner of inset
TTL	Absolute latitude of lower left corner
NVL	Absolute longitude of upper left corner
TVL	Absolute latitude of upper left corner
NTR	Absolute longitude of upper right corner
TTR	Absolute latitude of upper right corner
NVR	Absolute landude of lower right corner
14 4 10	Trooting tonginue of lower right corner

TABLE B-2. SOURC field descriptions - Continued.

FIELD	NAME VALUE DEFINITIONS
TVR	Absolute latitude of lower right corner
NRL	Relative longitude of lower left corner
TRL	Relative latitude of lower left corner
NSL	Relative longitude of upper left corner
TSL	Relative latitude of upper left corner
NRR	Relative longitude of upper right corner
TRR	Relative latitude of upper right corner
NSR	Relative longitude of lower right corner
TSR	Relative latitude of lower right corner

For each legend...

NAM	Name of legend
BAD	Name of image file (IID)

APPENDIX C

SENSOR PARAMETERS DATA EXTENSION

C.1 SCOPE

This appendix is intended to describe the sensor parameters data extension (SNSPS), containing the image auxiliary data (relevant to the capture of images by a sensor and its associated platform (aircraft, satellite...). These parameters should allow a capture location model of the sensor to accurately compute the location of any pixel of the image.

C.2 APPLICABLE DOCUMENTS

The applicable documents in section 2 MIL-STD-2500B apply to this appendix.

C.3 DEFINITIONS

The definitions in section 3 MIL-STD-2500B apply to this appendix.

C.4 GENERAL REQUIREMENTS

Hereafter are specified the general parameters defining the attributes of the image, sensor and platform (called basic parameters), that are most currently used. These basic parameters are :

- identification of sensor and platform,
- date and time of capture,
- identification of bands of image at capture stage,
- resolution and pixel spacing (space sampling) at capture stage,
- processing level of image (if any),
- attitude of sensor.

In addition, a way to include specific parameters for one s pecific sensor/platform (called additional auxiliary information) is proposed by giving the related information, for each specific parameter: identification, format, unit and value.

For some sensors, the number of specific parameters can be significant; in that case, a better solution can be the definition of a dedicated sensor data extension.

C.5 DETAILED REQUIREMENTS

C.5.1 SNSPS - Sensor parameters data extension. The user defined fields of the SNSPS data extension are detailed in table C-1, together with their descriptions. The attitude data are given in a relative orbital referential of the sensor. The additional auxiliary parameters can be either character strings, or integer or float numeric values. The auxiliary parameter value format discriminates between the 3 possible cases. The precision (and unit) of the numeric value allow for the accuracy required by the location model.

TABLE C-1. <u>SNSPS - Sensor parameters data extension</u>. (TYPE "R" = Required "C" = Conditional)

EIEI D	(TYPE "R" = Required "C" = Co		TALLEDANCE	/ / / D.D.
FIELD	NAME	SIZE	VALUE RANGE	TYPE
CETAG	<u>Unique Extension Identifier</u> .	5	BCS-A SNSPS	R
CEVER	Version.	1	BCS-A A	R
CEL	Length of Data to Follow (e.g., length of data in tag data field).	5	BCS-N 2 + NUM_BAND * 15+ 257 + NUM_AUX * (34 (if APF = I) otherwise 44) + 12 + NUM_COO*30	R
The following	fields define SNSPS			
NUM_BAND	Number of Bands of sensor image at capture	2	BCS-N	R
For each band	(the following 3 fields only appear when NUM_B	AND is not	00)	
BID	Original Scene Band Identification (original sensor image product)	5	BCS-A	R
WS1	Signal Lower Limit (in Nanometers for Wavelength)	5	BCS-N	R
WS2	Signal Upper Limit (in Nanometers for Wavelength)	5	BCS-N	R
		1		.
REX	Resolution E-W Direction	6	BCS-N	R
REY	Resolution N-S Direction	6	BCS-N	R
GSX ¹	Ground Sample Distance E-W Direction. Ground pixel spacing (sampling) at capture stage measured at pixel GSL.	6	BCS-N	R
GSY	Ground Sample Distance N-S Direction. Ground pixel spacing (sampling) at capture stage measured at pixel GSL.	6	BCS-N	R
GSL	Location of pixel for GSX and GSY	12	BCS-A (e.g UPPER LEFT, LOWER LEFT, UPPER RIGHT, LOWER RIGHT, CENTER)	R
UNIRES	Unit for resolution and ground sample distance	3	BCS-A (See Table G-1)	R
Basic_Auxillia	ry_Parameters	•		•
PLTFM	Platform Name ex.: SPOT3	8	BCS-A	R
INS	Sensor or Instrument Name ex.: HRV1	8	BCS-A	R
MOD	Spectral Mode ex.: PAN	4	BCS-A	R
PRL	Processing Level ex.: 1A	5	BCS-A	R

 1 GSX can be equal to REX (e.g for SPOT images in PAN mode, REX = GSX = 10 m) or different (e.g for ERS1 SAR PRI images, REX = 27 m, GSX = 12.5 m)

TABLE C-1. SNSPS - Sensor parameters data extension - Continued.

FIELD	NAME	SIZE	VALUE RANGE	TYPE
CDV07	Acquisition Date	8	BCS-A (YYYYMMDD)	R
ACT	Acquisition Time (seconds)	14	BCS-A	R
ANG	Incidence Angle at Original Scene Centre	7	BCS-N)	R
UNIANG	Unit of Incidence Angle	3	BCS-A	R
UNIANG	Clift of incidence Aligie	3	(See Table G-1)	IV.
ALT	Altitude of Sensor	9	BCS-N	R
			(+/-AAAA.AAA)	
UNIALT	Unit of Altitude	3	BCS-A	R
			(See Table G-1)	
LON	WGS84 Longitude of Original Scene	10	BCS-N (+/-SSSSSS.SS)	R
	Centre			
LAT	WGS84 Latitude of Original Scene Centre	10	BCS-N (+/-SSSSSS.SS)	R
SAZ	Solar Azimuth at Original Scene Centre	7	BCS-N (+/-DDD.DD)	R
SEL	Solar Elevation at Original Scene Centre	7	BCS-N {+/-DDD.DD}	R
UNISAE	Unit of Solar Angles (Decimal degrees)	3	BCS-A	R
			(See Table G-1)	
ROL	Roll of the Sensor at Original Scene Centre	7	BCS-N {+/-DDD.DD}	R
PIT	Pitch of the Sensor at Original Scene Centre	7	BCS-N {+/-DDD.DD}	R
YAW	Yaw of the Sensor at Original Scene Centre	7	BCS-N {+/-DDD.DD}	R
UNIRPY	Unit of Attitude Angles	3	BCS-A	R
	<u> </u>		(See Table G-1)	
PXT	Pixel Time (start time of acquisition)	14	BCS-N	R
UNIPXT	Unit of Pixel Time (S)	3	BCS-A	R
			(See Table G-1)	
ROS	Roll Speed at Original Scene Centre	22	BCS-N	R
PIS	Pitch Speed at Original Scene Centre	22	BCS-N	R
YAS	Yaw Speed at Original Scene Centre	22	BCS-N	R
UNISPE	Unit of Attitude Speed	3	BCS-A	R
			(See Table G-1)	
NUM_AU	Number of Auxiliary Parameters	2	BCS-N	R
X				
	nal auxiliary parameter (the following fields only appear		1_AUX is not 00)	l D
*API	Auxiliary Parameter ID	20	DCC A	R
APF	Auxiliary Parameter Value Format	1	BCS-A {I R A}	R
UNIAPX	Unit of Auxiliary Parameter	3	BCS-A	R
			(See Table G-1)	
APN	Auxiliary Parameter Integer Value	10	BCS-N	С
APR	Auxiliary Parameter Real Value	20	BCS-N	С
APA	Auxiliary Parameter Characters String Value	20	BCS-A	С
BAD	Identifier of Derived Image layer (Image ID)	10	BCS-A	R
NUM_COO	Number of Coordinates in Bounding	2	BCS-N	R
	Polygon		(04 - 99)	
For each coordin				
LON	Longitude/Easting of Point	15	BCS-N	R
			± ddd.ddddddddd /	
			± mmmmmmmmmmm.	
			m	

TABLE C-1. SNSPS - Sensor parameters data extension - Continued.

FIELD	NAME	SIZE	VALUE RANGE	TYPE
LAT	Latitude/Northing of Point	15	BCS-N ± 0dd.dddddddddd / ± mmmmmmmmmm. m	R

APPENDIX D

SAMPLE NITF FILE STRUCTURE WITH LOCATION GRIDS

D.1 SCOPE

The example given here is that of NITF file for the exchange of a non rectified image, with 2 associated geographic grids, one at minimum elevation on the image area (GRID1, with ZVL = 100 m), the other at maximum elevation on the image area (GRID2, with ZVL = 200 m).

D.2 APPLICABLE DOCUMENTS

The applicable documents in section 2 MIL-STD-2500B apply to this appendix.

D.3 DEFINITIONS

The definitions in section 3 MIL-STD-2500B apply to this appendix.

D.4 GENERAL REQUIREMENTS

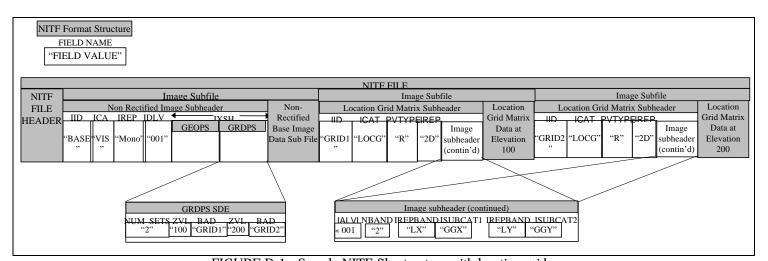


FIGURE D-1. Sample NITF file structure with location grids.

The coding of bands values BandX and BandY of location grid matrix data will be sequential or interleaved depending on IMODE value.

APPENDIX E

DIGEST DATE AND NAVIGATIONAL SYSTEM TYPE

E.1 SCOPE

TBD

E.2 APPLICABLE DOCUMENTS

The applicable documents in section 2 MIL-STD-2500B apply to this appendix.

E.3 DEFINITIONS

The definitions in section 3 MIL-STD-2500B apply to this appendix.

E.4 GENERAL REQUIREMENTS

 $E.4.1 \ \underline{DIGEST\ calendar\ date\ type}. \ CDP\ values\ give\ the\ type\ of\ report\ or\ activity\ ;\ the\ specified\ values\ are\ (From\ DIGEST\ Part\ 4\ -\ Annex\ B\ :\ FACC\ Codes)\ :$

TABLE E-1. DIGEST Calendar date type.

VALUE	DEFINITION
0	Unknown
1	Aerial photography
2	Air information
3	Approximate
4	Field classification
5	Compilation
6	Copyright
7	Creation
8	Digitizing
9	Distribution/Dispatching
10	Downgrading
11	Drafting/Scribing/Drawing
12	Edition
13	Field examination
14	Intelligence
15	Date interpretable
16	Processing
17	Print/Publication
18	Receipt
19	Source
20	Earliest date of source
21	Latest date of source
22	Specifications
23	Survey
24	Up-to-dateness/revision
25	Map Edit
26	Information as of
27	Perishable information date
28	Cycle date

TABLE E-1. DIGEST Calendar date type - Continued.

VALUE	DEFINITION
29	Significant date
30	Date of magnetic information
999	Other

E.4.2 <u>DIGEST Navigational system type</u>. NST values give the type of equipment or system used in electronic navigation (primary system); the specified values are (From DIGEST Part 4 - Annex B: FACC Codes):

TABLE E-2. DIGEST Navigational system type.

	DEFINITION
0	Unknown
1	Circular Radio Beacon
2	CONSOL
3	DECCA
4	Radio direction finding
5	Directional Radio Beacon
6	Distance finding
7	Long Range Air Navigation System (LORAN)
8	OMEGA
9	Other
10	Radar Responder Beacon (RACON)
11	Radar
12	Radio
13	Radio Telephone
14	VALUE INTENTIONALLY LEFT BLANK
15	TV
16	Microwave
17	Non-Directional Radio Beacon (NDB)
18	NDB / Distance Measuring Equipment (NDB/DME)
19	Radio Range (RNG)
20	VHF Omni Directional Radio Range (VOR)
21	VHF Omni Directional (VOR/DME)
22	VHF Omni Directional (VORTAC)
23	Tactical Air Navigation Equipment (TACAN)
24	Instrument Landing system (ILS)
25	Instrument Landing system / Distance Measuring Equipment (ILS/DME)
26	Localizer (LOC)
27	Localizer / Distance Measuring Equipment (LOC/DME)
28	Simplified Directional Facility (SDF)
29	Landing Distance Available (LDA)
30	Microwave Landing System (MLS)
31	Fan Marker
32	Bone Marker
33	Radio Telegraph
34	Ground Controlled Approach (GCA)
35	Radar Antenna
36 37	VALUE INTENTIONALLY LEFT BLANK Precision Approach Radar (PAR)

TABLE E-2. DIGEST Navigational system type.

VALUE	DEFINITION
38	Aeronautical Radio
39	VALUE INTENTIONALLY LEFT BLANK
40	Radio Beacon
41	Rotating Loop Radio Beacon
42	Visual Flight Rules (VFR) Test Signal Maker
43	VALUE INTENTIONALLY LEFT BLANK
44	Consol Radio Beacon
45	Radar station
46	Aeronautical Radio Range
47	Hifix
48	Hyperfix
49	Tricolor panel
50	Radio Station
51	Radiobeacon, type unknown
52	None
53	QTG Station (R)
54	Ramark
55	Radar reflector
56	Locator (LO)
57	Localizer (LLZ)
58	Distance Measuring Equipment (DME)
999	Other

APPENDIX F

GEODETIC CODES AND PARAMETERS

F.1 SCOPE

TBD

F.2 APPLICABLE DOCUMENTS

The applicable documents in section 2 MIL-STD-2500B apply to this appendix.

F.3 DEFINITIONS

The definitions in section 3 MIL-STD-2500B apply to this appendix.

F.4 GENERAL REQUIREMENTS

The 4 main geodetic concepts in this chapter are ellipsoid, datum, projection and grid system.

A geodetic datum includes an ellipsoid as one of its defining components. A grid system includes a datum and a projection among its defining components. The way in which geodetic datum, ellipsoid, grid and projection are inter-related is shown in figure F-1.

Concept Relationship Diagram Each arrow means " is an input which helps to define"		
Geodetic Datum	Æ	Grid System
Ellipsoid		Projection

FIGURE F-1. Concept Relationships.

The codes identifying ellipsoid, datum, projection and grid are listed in tables F-1, F-2, F-5 and F-6.

It should be noted that the grid codes in table F-6 are allocated to both grid systems and grid categories. A grid category includes a number of different grids, with variations in geodetic datum and/or zone of application. The most obvious example is Universal Transverse Mercator.

F.5 DETAILED REQUIREMENTS

F.5.1 <u>Ellipsoid codes</u>. The parameters (semimajor axis a and inverse flattening 1/f) are purely to assist ellipsoid identification. The abbreviation "*Alt:*" is used to denote alternative codes originating from DIGEST 1.2, which are included for backward compatibility. In some cases, ellipsoids have come into existence as part of a datum definition. As a result, some ellipsoids are known by the same name as the datum, although the codes will differ. Note the presence of special codes: NO for no ellipsoid, ZY for other known ellipsoid and ZZ for unknown ellipsoid.

TABLE F-1. DIGEST Ellipsoid codes.

ELLIPSOID	PARAMETERS (a, 1/f)	ELLIPSOID CODE
Airy (1830)	(6377563.396, 299.3249647)	AA
71119 (1000)	(0077000.000, 200.0210017)	Alt: AAY
US - Modified Airy	(6377340.189, 299.3249647)	AM
UK - Airy Modified	(00000000000000000000000000000000000000	Alt: AAM
Australian National (1966)	(6378160.000, 298.2500000)	AN
APL 4.5 (1968)	(6378144.000, 298.2300000)	AP
Average Terrestrial System 1977	(6378135.000, 298.2570000)	AT
Airy (War Office)	(6377542.178, 299.3250000)	AW
Bessel (Modified)	(6377492.018, 299.1528000)	BM
Bessel 1841 (Namibia)	(6377483.865, 299.1528128)	BN
US - Bessel 1841 (Ethiopia, Indonesia, Japan, Korea)	(6377397.155, 299.1528128)	BR
UK - Bessel (1841) Revised		
Clarke 1858	(6378235.600, 294.2606768)	CA
Clarke 1858 (Modified)	(6378293.645, 294.2600000)	СВ
Clarke 1866	(6378206.400, 294.9786982)	CC
772 07 7 700	(0.2.2.2.2.2.2.2.2.2.2.2.2.2.2.2.2.2.2.2	Alt: CLK
US - Clarke 1880	(6378249.145, 293.4650000)	CD
UK - Clarke 1880 Modified	(0070040 145, 000 4000077)	Alt: CLJ
Clarke 1880 (Cape)	(6378249.145, 293.4663077)	CE
Clarke 1880 (Palestine)	6378300.782, 293.4663077)	CF
Clarke 1880 (IGN)	(6378249.200, 293.4660208)	CG
Clarke 1880 (Syria)	(6378247.842, 293.4663517)	CI
Clarke 1880 (Fiji)	(6378301.000, 293.4650000)	CJ
Clarke 1880 (Unspecified)	(-,-)	CL
Danish (1876) or Andrae Delambre 1810	(6377104.430, 300.0000000	DA
	(6376985.228, 308.6400000)	DB
Delambre (Carte de France)	(6376985.000, 308.6400000) (6377276.345, 300.8017000)	DC EA
US - Everest (India 1830) UK - Everest (1830)	(6377276.345, 300.8017000)	EA
US - Everest (1830) US - Everest (Brunei and E. Malaysia	(6377298.556, 300.8017000)	EB
(Sabah and Sarawak))	(0377298.330, 300.8017000)	ED
UK - Everest (Borneo)		
US - Everest (India 1956)	(6377301.243, 300.8017000)	EC
UK - Everest (India)	UK takes 1/f as 300.8017255.	
US - Everest (W. Malaysia 1969)	(6377295.664, 300.8017000)	ED
UK - Everest (Malaya RSO)	(00000000000000000000000000000000000000	
US - Everest (W. Malaysia and Singapore 1948)	(6377304.063, 300.8017000)	EE
UK - Everest (Malaya RKT)		
Everest (Pakistan)	(6377309.613, 300.8017000)	EF
Everest (Unspecified)	(-,-)	EV
US - Modified Fischer 1960 (South Asia)	(6378155.000, 298.3000000)	FA
UK - Fischer 1960 (South Asia)		
Fischer 1968	(6378150.000, 298.3000000)	FC
Fischer 1960 (Mercury)	(6378166.000, 298.3000000)	FM
Germaine (Djibouti)	(6378284.000, 294.0000000)	GE

TABLE F-1. <u>DIGEST Ellipsoid codes</u> - Continued.

ELLIPSOID	PARAMETERS (a, 1/f)	ELLIPSOID CODE
Hayford 1909	The original version, based	HA
(6378388.000, 296.9592630)	on $a = 6378388$, $b = 6356909$.	
Helmert 1906	(6378200.000, 298.3000000)	HE
Hough 1960	(6378270.000, 297.0000000)	НО
Indonesian National (1974)	(6378160.000, 298.2470000)	ID
US - International 1924	(6378388.000, 297.0000000)	IN
UK - International		Alt: INT
Krassovsky (1940)	(6378245.000, 298.3000000)	KA
		Alt: KRA
Krayenhoff 1827	(6376950.400, 309.6500000)	KB
No ellipsoid		NO
NWL-8E	(6378145.000, 298.2500000)	NW
Plessis Modified	(6376523.000, 308.6400000)	PM
Plessis Reconstituted	(6376523.994, 308.6248070)	PR
Geodetic Reference System 1967	(6378160.000, 298.2471674)	RE
Geodetic Reference System 1980	(6378137.000, 298.2572221)	RF
South American	(6378160.000, 298.2500000)	SA
Soviet Geodetic System 1985	(6378136.000, 298.2570000)	SG
Ellipsoid Junction		SJ
Soviet Geodetic System 1990	(6378136.000, 298.2578393)	SN
Struve 1860	(6378298.300, 294.7300000)	ST
Svanberg	(6376797.000, 304.2506000)	SV
Walbeck 1819 (Planheft 1942)	(6376895.000, 302.7821565)	WA
Walbeck 1819 (AMS 1963)	(6376896.000, 302.7800000)	WB
World Geodetic System 1966	(6378145.000, 298.2500000)	WC
World Geodetic System 1972	(6378135.000, 298.2600000)	WD
<i>y</i>	(Alt: WGC
World Geodetic System 1984	(6378137.000, 298.2572236)	WE
<i>y</i>	(Alt: WGE
World Geodetic System (Unspecified)	(-,-)	WF
US - War Office 1924 (McCaw)	(6378300.000, 296.0000000)	WO
UK - War Office 1924	,	
World Geodetic System 1960	(6378165.000, 298.3000000)	WS
Other Known Ellipsoid		ZY
Unknown Ellipsoid		ZZ

F.5.2 <u>Datum codes</u>. Table F-2 provides the allowable datums and their codes for the Geodetic Datum fields. Sounding Datum and the Vertical Reference System field usage are also covered in the Feature and Attribute Coding Catalogue (Part 4).

In some cases a geodetic datum with a 3-letter code is followed by 4-letter codes referring to the same datum but specifying particular regions. See, for example, codes AINA and AINB which follow AIN. The 4-letter codes are not different datums, but "regional" solutions to the datum. Regional solutions represent regional variations in the relationship between the datum and WGS 1984. Use of the 4-letter code is recommended when there is a need to identify that relationship.

Unless indicated otherwise at the end of the datum name, the Zero Meridian is always Greenwich. Datums with a zero meridian other than Greenwich have "1" as a 4th character in the datum code.

To assist the process of matching ellipsoids to datums, ellipsoid codes are shown in the final column. The abbreviation "*Alt:*" is used to denote alternative codes originating from DIGEST 1.2, which are included for backward compatibility.

Note the presence of special codes:

- Geodetic Datums (Table F-2): UND for undetermined datum and ZYX for other known datum.
- Sounding Datums (Table F-4): ZYX for other known sounding datum and ZZZ for unknown.

TABLE F-2. DIGEST Geodetic Datum Codes.

GEODETIC DATUMS	DATUM	ELLIPSOID
(Horizontal Datums can also be used as Vertical Datums)	CODE	CODE
Adindan	ADI	CD
Adindan (Ethiopia)	ADIA	CD
Adindan (Sudan)	ADIB	CD
Adindan (Mali)	ADIC	CD
Adindan (Senegal)	ADID	CD
Adindan (Burkina Faso)	ADIE	CD
Adindan (Cameroon)	ADIF	CD
Adindan (Mean value: Ethiopia and Sudan)	ADIM	CD
Afgooye (Somalia)	AFG	KA
Antigua Island Astro 1943	AIA	CD
Ain el Abd 1970	AIN	IN
Ain el Abd 1970 (Bahrain Island)	AINA	IN
Ain el Abd 1970 (Saudi Arabia)	AINB	IN
American Samoa Datum 1962	AMA	CC
Amersfoort 1885/1903 (Netherlands)	AME	BR
Anna 1 Astro 1965 (Cocos Islands)	ANO	AN
Approximate Luzon Datum (Philippines)	APL	CC
Arc 1950	ARF	CD
Arc 1950 (Botswana)	ARFA	CD
Arc 1950 (Lesotho)	ARFB	CD
Arc 1950 (Malawi)	ARFC	CD
Arc 1950 (Swaziland)	ARFD	CD
Arc 1950 (Zaire)	ARFE	CD
Arc 1950 (Zambia)	ARFF	CD
Arc 1950 (Zimbabwe)	ARFG	CD
Arc 1950 (Burundi)	ARFH	CD
Arc 1950 (Mean value: Botswana, Lesotho, Malawi,	ARFM	CD
Swaziland, Zaire, Zambia, and Zimbabwe)		

 $TABLE \ F-2. \ \underline{DIGEST \ Geodetic \ Datum \ Codes} - Continued.$

CEODETIC DATUM		EL LIDCOID
GEODETIC DATUMS	DATUM	ELLIPSOID
(Horizontal Datums can also be used as Vertical Datums)	CODE	CODE
Arc 1960	ARS	CD
Arc 1960 (Kenya)	ARSA	CD
Arc 1960 (Tanzania)	ARSB	CD
Arc 1960 (Mean value: Kenya, Tanzania)	ARSM	CD
Arc 1935 (Africa)	ART	CD
Ascension Island 1958 (Ascension Island)	ASC	IN
Montserrat Island Astro 1958	ASM	CD
Astro Station 1952 (Marcus Island)	ASQ	IN
Astro Beacon "E" (Iwo Jima Island)	ATF	IN
Average Terrestrial System 1977, New Brunswick	ATX	AT
Australian Geod. 1966 (Australia and Tasmania Is.)	AUA	AN
Australian Geod. 1984 (Australia and Tasmania Is.)	AUG	AN
Djakarta (Batavia) (Sumatra Island, Indonesia)	BAT	BN
Djakarta (Batavia) (Sumatra Island, Indonesia) with Zero Meridian	BAT1	BN
Djakarta		
Bekaa Base South End (Lebanon)	BEK	CG
Belgium 1950 System (Lommel Signal, Belgium)	BEL	IN
Bermuda 1957 (Bermuda Islands)	BER	CC
Bissau (Guinea-Bissau)	BID	IN
Bogota Observatory (Colombia)	ВОО	IN
Bogota Observatory (Colombia) with Zero Meridian Bogota	BOO1	IN
Bern 1898 (Switzerland)	BRE	BR
Bern 1898 (Switzerland) with Zero Meridian Bern	BRE1	BR
Bukit Rimpah (Bangka & Belitung Islands, Indonesia)	BUR	BR
Cape Canaveral (Mean value: Florida and Bahama Islands)	CAC	CC
Campo Inchauspe (Argentina)	CAI	IN
Camacupa Base SW End (Campo De Aviacao, Angola)	CAM	CD
Canton Astro 1966 (Phoenix Islands)	CAO	IN
Cape (South Africa)	CAP	CE
Camp Area Astro (Camp McMurdo Area, Antarctica)	CAZ	IN
S-JTSK, Czechoslavakia (prior to 1 Jan 1993)	CCD	BN
Carthage (Tunisia)	CGE	CG
Compensation Géodétique du Québec 1977	CGX	CC
Chatham 1971 (Chatham Island, New Zealand)	CHI	IN
Chua Astro (Paraguay)	CHU	
Corrego Alegre (Brazil)	COA	IN
Conakry Pyramid of the Service Geographique (Guinea)	COV	CG
Guyana CSG67	CSG	-
Dabola (Guinea)	DAL	CD
DCS-3 Lighthouse, Saint Lucia, Lesser Antilles	DCS	CD
Deception Island, Antarctica	DID	CD
GUX 1 Astro (Guadacanal Island)	DOB	IN
Dominica Astro M-12, Dominica, Lesser Antilles	DOM	111
Easter Island 1967 (Easter Island)	EAS	IN
Wake-Eniwetok 1960 (Marshall Islands)	ENW	НО
European 1950 (Mean value)	EUR	IN
European 1730 (Mean value)	LUK	11/

 $TABLE \ F-2. \ \underline{DIGEST \ Geodetic \ Datum \ Codes} - Continued.$

CEODETIC DATUMC		EL LIDCOID
GEODETIC DATUMS (Havigantal Datums can also be used as Vertical Datums)	DATUM CODE	ELLIPSOID CODE
(Horizontal Datums can also be used as Vertical Datums) European 1950 (Norway and Finland)		IN
European 1950 (Norway and Filiand) European 1950 (Portugal and Spain)	EURC EURD	IN
European 1950 (Cyprus)	EURE	IN
	EURF	IN
European 1950 (Egypt) European 1950 (England, Channel Islands, Scotland, and		IN
Shetland Islands)	EURG	IIN
European 1950 (Iran)	EURH	IN
European 1950 (Sardinia)	EURI	IN
	EURJ	IN
European 1950 (Sicily)		IN
European 1950 (England, Channel Islands, Ireland, Northern	EURK	IIN
Ireland, Scotland, Shetland Islands, and Wales)	EUDI	INI
European 1950 (Malta)	EURL	IN
European 1950 (Mean value: Austria, Belgium, Denmark,	EURM	IN
Finland, France, Federal Republic of Germany, Gibraltar, Greece, Italy, Luxembourg, Netherlands, Norway, Portugal,		
Spain, Sweden, & Switzerland)		
European 1950 (Iraq, Israel, Jordan, Kuwait, Lebanon, Saudi	EURS	IN
Arabia, and Syria)	EURS	1111
European 1950 (Tunisia)	EURT	IN
European 1930 (Tunisia) European 1979 (Mean value: Austria, Finland, Netherlands, Norway?	EUS	IN
Spain, Sweden, and Switzerland)	EUS	111
Oman (Oman)	FAH	CD
Observatorio Meteorologico 1939 (Corvo and Flores Islands, Azores)	FLO	IN
Fort Thomas 1955 (Nevis, St Kitts, Leeward Islands)	FOT	CD
GAN 1970 (Addu Atoll, Republic of Maldives)	GAA	IN
Gandajika Base (Zaire)	GAN	IN
Geodetic Datum 1949 (New Zealand)	GEO	IN
DOS 1968 (Gizo Island, New Georgia Islands)		IN
	GIZ	
Graciosa Base SW (Faial, Graciosa, Pico, Sao Jorge, and Terceira Island, Azores)	GRA	IN
Greek Datum, Greece	GRK	BR
Greek Geodetic Reference System 1987 (GGRS 87)	GRX	RF
Gunong Segara (Kalimantan Island, Indonesia)	GSE	BR
Gunong Serindung	GSF	BR
Guam 1963	GUA	CC
Herat North (Afganistan)	HEN	IN
· · · ·		BR
Hermannskogel Provisional South Chilean 1963 (or Hito XVIII 1963) (S. Chile,	HER	IN
	HIT	IIN
53°S)	1110	DI
Hjörsey 1955 (Iceland)	HJO	IN
Hong Kong 1963 (Hong Kong)	HKD	IN
Hong Kong 1929	НКО	CA
Hu-Tzu-Shan	HTN	IN
Hungarian 1972	HUY	RE
Bellevue (IGN) (Efate and Erromango Islands)	IBE	IN
Indonesian 1974	IDN	ID
Indian	IND	
Indian (Thailand and Vietnam)	INDA	

TABLE F-2. DIGEST Geodetic Datum Codes -		ELLIDCOID
GEODETIC DATUMS	DATUM	ELLIPSOID
(Horizontal Datums can also be used as Vertical Datums)	CODE	CODE
Indian (Bangladesh)	INDB	EA
Indian (India and Nepal)	INDI	EC
Indian (Pakistan)	INDP	EF
Indian (1954)	INF	EA
Indian 1954 (Thailand)	INFA	EA
Indian 1960	ING	EA
Indian 1960 (Vietnam: near 16°N)	INGA	EA
Indian 1960 (Con Son Island (Vietnam))	INGB	EA
Indian 1975	INH	EA
Indian 1975 (Thailand)	INHA	EA
Ireland 1965 (Ireland and Northern Ireland)	IRL	AM
ISTS 061 Astro 1968 (South Georgia Islands)	ISG	IN
ISTS 073 Astro 1969 (Diego Garcia)	IST	IN
Johnston Island 1961 (Johnston Island)	JOH	IN
Kalianpur (India)	KAB	EC
Kandawala (Sri Lanka)	KAN	EA
Kertau 1948 (or Revised Kertau) (West Malaysia and Singapore)	KEA	EE
KCS 2, Sierra Leone	KCS	WO
Kerguelen Island 1949 (Kerguelen Island)	KEG	IN
Korean Geodetic System (Coree Du Sud)	KGS	RF
KKJ (or Kartastokoordinaattijarjestelma), Finland	KKX	IN
Kusaie Astro 1951	KUS	IN
Kuwait Oil Company (K28)	KUW	CD
L.C. 5 Astro 1961 (Cayman Brac Island)	LCF	CC
Leigon (Ghana)	LEH	CG
Liberia 1964 (Liberia)	LIB	CD
Lisbon (Castelo di São Jorge), Portugal	LIS	
Local Astro.	LOC	
Loma Quintana (Venezuela)	LOM	IN
Luzon	LUZ	CC
Luzon (Philipines except Mindanao Island)	LUZA	CC
Luzon (Mindanao Island)	LUZB	CC
Marco Astro (Salvage Islands)	MAA	IN
Martinique Fort-Desaix	MAR	IN
Massawa (Eritrea, Ethiopia)	MAS	BR
Manokwari (West Irian)	MAW	
Mayotte Combani	MCX	
Mount Dillon, Tobago	MDT	
Merchich (Morocco)	MER	CG
Midway Astro 1961 (Midway Island)	MID	IN
Mahe 1971 (Mahe Island)	MIK	CD
Minna	MIN	CD
Minna (Cameroon)	MINA	CD
Minna (Nigeria)	MINB	CD
Mannheim (Germany)	MNM	
Rome 1940 (or Monte Mario 1940), Italy	MOD	IN
(1.202	1

CEODETIC DATUM		ELLIDCOID
GEODETIC DATUMS (Horizontal Datums can also be used as Vertical Datums)	DATUM CODE	ELLIPSOID CODE
Rome 1940 (or Monte Mario 1940), Italy, with Zero Meridian Rome	MOD1	IN
Montjong Lowe	MOL	BR
M'Poraloko (Gabon)	MPO	CD
Viti Levu 1916 (Viti Levu Island, Fiji Islands)	MVS	CD
Nahrwan	NAH	CD
Nahrwan (Masirah Island, Oman)	NAHA	CD
Nahrwan (United Arab Emirates)	NAHB	CD
Nahrwan (Saudi Arabia)	NAHC	CD
Naparima (BWI Trinidad and Tobago)	NAP	IN
North American 1983	NAR	RF
North American 1983 (Alaska, excluding Aleutian Islands)	NARA	RF
North American 1983 (Canada)	NARB	RF
North American 1983 (CONUS)	NARC	RF
North American 1983 (Mexico and Central America))	NARD	RF
North American 1983 (Aleutian Islands)	NARE	RF
North American 1983 (Hawaii)	NARH	RF
North American 1927 (Mean value)	NAS	CC
North American 1927 (Eastern US)	NASA	CC
North American 1927 (Western US)	NASB	CC
North American 1927 (Mean value: CONUS)	NASC	CC
North American 1927 (Alaska)	NASD	CC
North American 1927 (Mean value: Canada)	NASE	CC
North American 1927 (Alberta and British Columbia)	NASF	CC
North American 1927 (Newfoundland, New Brunswick, Nova	NASG	CC
Scotia and Quebec)		
North American 1927 (Manitoba and Ontario)	NASH	CC
North American 1927 (Northwest Territories and	NASI	CC
Saskatchewan)		
North American 1927 (Yukon)	NASJ	CC
North American 1927 (Mexico)	NASL	CC
North American 1927 (Central America - Belize, Costa Rica, El	NASN	CC
Salvador, Guatemala, Honduras, and Nicaragua)		
North American 1927 (Canal Zone)	NASO	CC
North American 1927 (Caribbean, Barbados,	NASP	CC
Caicos Islands, Cuba, Dominican Republic, Grand		
Cayman, Jamaica, Leeward Islands, and Turks Islands)	371.00	~~
North American 1927 (Bahamas, except San Salvador Island)	NASQ	CC
North American 1927 (San Salvador Island)	NASR	CC
North American 1927 (Cuba)	NAST	CC
North American 1927 (Hayes Peninsula, Greenland)	NASU	CC
North American 1927 (Aleutian Islands East of 180°W)	NASV	CC
North American 1927 (Aleutian Islands West of 180°W)	NASW	CC
New French or Nouvelle Triangulation Française (NTF) with Zero	NFR1	CG
Meridian Paris	Alt: FDA	
North Sahara 1959	NSD	CD
Ocotopeque, Guatemala	OCO	
Belgium 1972 (Observatoire d'Uccle)	ODU	IN

GEODETIC DATUMS	TABLE F-2. DIGEST Geodetic Datum Codes - C		ELLIDGOID
Old Egyptian (Egypt)			
Ordnance Survey of Great Britain OGB AA Ordnance Survey G.B. 1936 (England) OGBA AA Ordnance Survey G.B. 1936 (England, Isle of Man, and Wales) OGBB AA Ordnance Survey G.B. 1936 (Scotland and Shetland Islands) OGBD AA Ordnance Survey G.B. 1936 (Mean value: England, Isle of Man, Scotland, Shetland, and Wales) OGBM AA Old Hawaiian OHA CC Old Hawaiian (Hawaii) OHAA CC Old Hawaiian (Kauai) OHAB CC Old Hawaiian (Maui) OHAB CC Old Hawaiian (Mean value) OHAD CC Old Hawaiian (Mean value) OHAD CC Old Observatory (Old), Norway OSL BR BR Padang Base West End (Sumatra, Indonesia) PAD BR Padang Base West End (Sumatra, Indonesia) with Zero Meridian PAD BR Palestine 1928 (Israel, Jordan) PAL CF Potsdam or Helmerturm (Germany) PDM IN Ayabelle Lighthouse (Djibouti) PHA CD Piccairn Astro 1967 (Pitcairn Island) PIT IN			
Ordnance Survey G.B. 1936 (England) OGBA (AA) AA Ordnance Survey G.B. 1936 (England, Isle of Man, and Wales) OGBB (AA) AA Ordnance Survey G.B. 1936 (Scotland and Shetland Islands) OGBC (AA) AA Ordnance Survey G.B. 1936 (Wales) OGBD (AA) AA Ordnance Survey G.B. 1936 (Wales) OGBM (AA) AA Ord Hawaiian (Man) (State Mawaiian (Man) (AB) (CC) Old Hawaiian (Maui) (CC) OHAA (CC) Old Hawaiian (Maui) (Maui) (Mawaiian (Maui) (Mawaiian (Maui) (Mawaiian (Maui) (Mawaiian (Maui) (Mawaiian (Mawaiiian (Mawaiiian (Mawaiiian (Mawaiiian (Mawaiiian (Mawaiiian (Mawaiiian (Mawaiiian (Mawaiiiian (Mawaiiiiinan (Mawaiiiiinan (Mawaiiiiiinan (Mawaiiiiiiiinan (Mawaiiiiiiiiiiiiiiiiiiiiiiiiiiiiiiiiiii	001		
Ordnance Survey G.B. 1936 (England, Isle of Man, and Wales) Ordnance Survey G.B. 1936 (Scotland and Shetland Islands) Ordnance Survey G.B. 1936 (Wales) Ordnance Survey G.B. 1936 (Mean value: England, Isle of Man, Scotland, Shetland, and Wales) Old Hawaiian Old Hawaiian Old Hawaiian Old Hawaiian Old Hawaiian (Maui) Old Hawa	·		
Wales) Ordnance Survey G.B. 1936 (Scotland and Shetland Islands) OGBC AA Ordnance Survey G.B. 1936 (Wales) OGBD AA Ordnance Survey G.B. 1936 (Mean value: England, Isle of Man, Scotland, Shetland, and Wales) OGBM AA Old Hawaiian (Hawaii) OHAA CC Old Hawaiian (Kauai) OHAB CC Old Hawaiian (Maui) OHAC CC Old Hawaiian (Mean value) OHAM CC Old Hawaiian (Mean value) OHAM CC Oslo Observatory (Old), Norway OSL BR Padang Base West End (Sumatra, Indonesia) PAD BR Padang Base West End (Sumatra, Indonesia) with Zero Meridian PAD BR Palestine 1928 (Israel, Jordan) PAL CF Potsdam or Helmertturm (Germany) PDM IN Ayabelle Lighthouse (Djibouti) PHA CD Pitcairn Astro 1967 (Pitcairn Island) PIT IN Pico de las Nieves (Canary Islands) PLN IN Provisional South American 1956 (Bolivia) PRP IN Prov. S. American 1956 (Northern Chil			
Ordnance Survey G.B. 1936 (Scotland and Shetland Islands) Ordnance Survey G.B. 1936 (Wales) Ordnance Survey G.B. 1936 (Mean value: England, Isla of Man, Scotland, Shetland, and Wales) Old Hawaiian Old Hawaiian (Hawaii) Old Hawaiian (Hawaii) Old Hawaiian (Maui) Old H	· · · · · · · · · · · · · · · · · · ·	OGBB	AA
Ordnance Survey G.B. 1936 (Wales) OGBD AA Ordnance Survey G.B. 1936 (Mean value: England, Isle of Man, Scotland, Shetland, and Wales) OGBM AA Old Hawaiian OHA CC Old Hawaiian (Hawaii) OHAA CC Old Hawaiian (Maui) OHAB CC Old Hawaiian (Maui) OHAC CC Old Hawaiian (Mean value) OHAM CC Oslo Observatory (Old), Norway OSL BR Padang Base West End (Sumatra, Indonesia) PAD BR Padang Base West End (Sumatra, Indonesia) with Zero Meridian PAD BR Palestine 1928 (Israel, Jordan) PAL CF Potsdam or Helmertturm (Germany) PDM IN Ayabelle Lighthouse (Djibouti) PHA CD Pitcairn Astro 1967 (Pitcairn Island) PIT IN Pico de las Nieves (Canary Islands) PLN IN SE Base (Porto Santo) (Porto Santo & Madeira Islands) PLN IN Provisional South American 1956 PRP IN Prov. S. American 1956 (Bolivia) PRPA IN	,	0.070.0	
Ordnance Survey G.B. 1936 (Mean value: England, Isle of Man, Scotland, Shetland, and Wales) Old Hawaiian OHA CC Old Hawaiian (Hawaii) OHAB CC Old Hawaiian (Kauai) OHAB CC Old Hawaiian (Kauai) OHAB CC Old Hawaiian (Maui) OHAC CC Old Hawaiian (Mean value) OHAM CC Old Hawaiian (Mean value) OHAM CC Oslo Observatory (Old), Norway OSL BR Padang Base West End (Sumatra, Indonesia) Padang Base West End (Sumatra, Indonesia) Padang Base West End (Sumatra, Indonesia) Photsdam or Helmertturn (Germany) Ayabelle Lighthouse (Djibouti) PHA CD Pitcairn Astro 1967 (Pitcairn Island) Pitr IN Pico de las Nieves (Canary Islands) Prov. S. American 1956 (Bolivia) Prov. S. American 1956 (Northern Chile near 19°S) Prov. S. American 1956 (Southern Chile near 19°S) Prov. S. American 1956 (Columbia) Prov. S. American 1956 (Columbia) Prov. S. American 1956 (Ecuador) Prov. S. American 1956 (Ecuador) Prov. S. American 1956 (Venezuela) Prov.			
Isle of Man, Scotland, Shetland, and Wales Old Awaiian OHA CC			
Old Hawaiian (Hawaii) Old Hawaiian (Hawaii) Old Hawaiian (Kauai) Old Hawaiian (Maui) OHAB CC Old Hawaiian (Maui) OHAC CC Old Hawaiian (Mean value) Old Hawaiian (Old Hawaiian (Mean value) Old Hawaiian (Mean value) Old Hawaiian (Old Hawaiian (Nean value) Old Hawaiian (Nean value)		OGBM	AA
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TABLE F-2. DIGEST GEODETIC DATUM CODES - C		EL LIBGOID
GEODETIC DATUMS	DATUM	ELLIPSOID
(Horizontal Datums can also be used as Vertical Datums)	CODE	CODE
RT90, Stockholm, Sweden	RTS	BR
Santo (DOS) 1965 (Espirito Santo Island)	SAE	IN
South African (South Africa)	SAF	CD
Sainte Anne I 1984 (Guadeloupe)	SAG	~ .
South American 1969	SAN	SA
South American 1969 (Argentina)	SANA	SA
South American 1969 (Bolivia)	SANB	SA
South American 1969 (Brazil)	SANC	SA
South American 1969 (Chile)	SAND	SA
South American 1969 (Columbia)	SANE	SA
South American 1969 (Ecuador)	SANF	SA
South American 1969 (Guyana)	SANG	SA
South American 1969 (Paraguay)	SANH	SA
South American 1969 (Peru)	SANI	SA
South American 1969 (Baltra, Galapagos Islands)	SANJ	SA
South American 1969 (Trinidad and Tobago)	SANK	SA
South American 1969 (Venezuela)	SANL	SA
South American 1969 (Mean value: Argentina, Bolivia,	SANM	SA
Brazil, Chile, Columbia, Ecuador, Guyana, Paraguay,		
Peru, Trinidad, Tobago, and Venezuela)		
Sao Braz (Sao Miguel, Santa Maria Islands, Azores)	SAO	IN
Sapper Hill 1943 (East Falkland Islands)	SAP	IN
Schwarzeck (Namibia)	SCK	BN
Soviet Geodetic System 1985	SGA	SG
Soviet Geodetic System 1990	SGB	SG
Selvagem Grande 1938 (Salvage Islands)	SGM	IN
Astro Dos 71/4 (St. Helena Island)	SHB	IN
Sierra Leone 1960	SIB	CD
South Asia (Southeast Asia, Singapore)	SOA	FA
S-42 (Pulkovo 1942)	SPK	KA
St. Pierre et Miquelon 50	SPX	1071
Stockholm 1938 (Sweden)	STO	BR
Sydney Observatory, New South Wales, Australia	SYO	СВ
Tananarive Observatory 1925	TAN	IN
Tananarive Observatory 1925, with Zero Meridian Paris	TAN1	IN
Tristan Astro 1968 (Tristan da Cunha)	TDC	IN
Timbalai 1948 (Brunei and East Malaysia - Sarawak and Sabah)	TIL	EB
	+	ED
Timbali 1968	TIN	DD
Tokyo (Janan)	TOY	BR
Tokyo (Japan)	TOYA	BR
Tokyo (Korea)	TOYB	BR
Tokyo (Okinawa)	TOYC	BR
Tokyo (Mean value: Japan, Korea, and Okinawa)	TOYM	BR
Trinidad 1903	TRI	CA
Astro Tern Is. 1961 (Tern Island, Hawaii)	TRN	IN
Tübingen (Germany)	TUB	<u> </u>
Undetermined (processed as if WGS 84)	UND	

TABLE F-2. DIGEST Geodetic Datum Codes - Continued.

GEODETIC DATUMS	DATUM	ELLIPSOID
(Horizontal Datums can also be used as Vertical Datums)	CODE	CODE
Voirol 1875	VOI	CG
Voirol 1875 with Zero Meridian Paris	VOI1	CG
Voirol 1960, Algeria	VOR	CG
Voirol 1960, Algeria, with Zero Meridian Paris	VOR1	CG
Wake Island Astro 1952	WAK	
World Geodetic System 1960	WGA	WS
World Geodetic System 1966	WGB	WC
World Geodetic System 1972	WGC	WD
World Geodetic System 1984	WGE	WE
Yacare (Uruguay)	YAC	IN
Zanderij (Surinam)	ZAN	IN
Other Known Datum	ZYX	

TABLE F-3. <u>DIGEST Codes for Vertical Datums</u>.

VERTICAL DATUM REFERENCE	CODE
Geodetic (see Note 1)	GEOD
Mean Sea Level (see Note 2) with identification	MSL
Example: Mean Sea Level Singapore	

Note 1. All elevations in the dataset are referenced to the ellipsoid of the specified geodetic datum. Note 2. All elevations in the dataset are referenced to the measured geoid of the specified datum.

TABLE F-4. DIGEST Codes for Sounding Datums.

SOUNDING DATUM	CODE
Approximate Lowest Astronomical Tide	ALAT
Approximate Mean Low Water Tide	AMLLW
Approximate Mean Low Water	AMLW
Approximate Mean Low Water Springs	AMLWS
Approximate Mean Sea Level	AMSL
Chart Datum (Unspecified)	CD
Equinoctial Spring Low Water	ESLW
Highest Astronomical Tide	HAT
Higher High Water Large Tide	HHWLT
Highest Normal High Water	HNHR
Higher High Water	HRHW
Highest High Water	HTHW
High Water	HW
High Water Springs	HWS
International Great Lakes Datum 1985	IGLD
Indian Spring High Water	ISHW
Indian Spring Low Water	ISLW
Lowest Astronomical Tide	LAT
Local Datum (arbitrary datum defined by local harbour authority)	LD
Lower Low Water Large Tide	LLWLT
Lowest Low Water Springs	LLWS
Lower Low Water	LRLW
Lowest Low Water	LTLW

TABLE F-4. DIGEST Codes for Sounding Datums - Continued.

TABLE 1 4. DIGEST Codes for Sounding Datums	Commucu.
SOUNDING DATUM	CODE
Low Water	LW
Low Water Springs	LWS
Mean Higher High Water	MHHW
Mean Higher Water	MHRW
Mean High Water	MHW
Mean High Water Neaps	MHWN
Mean High Water Springs	MHWS
Mean Lower Low Water	MLLW
Mean Lower Low Water Springs	MLLWS
Mean Low Water	MLW
Mean Low Water Neaps	MLWN
Mean Low Water Springs	MLWS
Mean Sea	MSL
Mean Tide Level	MTL
Nearly Lowest Low Water	NLLW
Neap Tide	NT
Spring Tide	ST
VALUE INTENTIONALLY LEFT BLANK	VILB
Other Known Sounding Datum	ZYX
Unknown	ZZZ

F.5.3 <u>Projection code and parameters</u>. Table F-5 provides the allowable projections and their codes and parameters for the Dataset Map Projection Group. These codes and parameters are necessary for conversion of geographic coordinates to/from grid coordinates (as used on a map). Note that Easting False Origin and Northing False Origin are also needed.

The abbreviation "Alt:" is used to denote alternative codes originating from DIGEST 1.2, which are included for backward compatibility.

Note the presence of a special code ZY for other known projection.

TABLE F-5. DIGEST Projection Codes and Parameters.

PROJECTION	PROJ'N	PARAMETERS			
	CODE	1	2	3	4
Albers Equal-Area Conic	AC	Longitude of	Std. Parallel	Std. Parallel	Latitude of
		Origin	Nearer to	Farther from	Origin (see
			Equator	Equator	Note 5)
(Lambert) Azimuthal	AK	Longitude of	Latitude of	-	-
Equal-Area		Proj. Origin	Proj. Origin		
Azimuthal Equidistant	AL	Longitude of	Latitude of	-	-
		Proj. Origin	Proj. Origin		
Bonne	BF	Longitude of	Latitude of	Scale Factor at	-
		Proj. Origin	Proj. Origin	Proj. Origin	
Equirectangular (La Carte	CC	Longitude of	Latitude of	-	-
Parallélogramatique)		Central	True Scale		
		Meridian			

TABLE F-5. DIGEST Projection Codes and Parameters - Continued.

PROJECTION	PROJ'N	PARAMETERS PARAMETERS			
TROJECTION	CODE	1	2	3	4
Equidistant Conic with 1 Standard Parallel	СР	Longitude of Central Meridian	Latitude of Proj. Origin	Latitude of Standard Parallel	-
Cassini-Soldner	CS	Longitude of Proj. Origin	Latitude of Proj. Origin	-	-
Gnomonic	GN	Longitude of Proj. Origin	Latitude of Proj. Origin	-	-
Hotine Oblique Mercator based on 2 Points	HX	Scale Factor at Proj. Origin	Latitude of Proj. Origin	Longitude of 1st Point defining Central Line	Latitude of 1st Point defining Central Line
(Note the 5th and 6th Parameters shown right.)		Longitude of 2nd Point defining Central Line	Latitude of 2nd Point defining Central Line	-	-
Equidistant Conic with 2 Standard Parallels	KA	Longitude of Central Meridian	Latitude of Origin (see Note 5)	Latitude of Standard Parallel Nearer to Equator	Latitude of Standard Parallel Farther from Equator
Laborde	LA	Longitude of Proj. Origin	Latitude of Proj. Origin	Scale Factor at Proj. Origin	-
Lambert Conformal Conic (see Note 1)	LE	Longitude of Origin	Std. Parallel Nearer to Equator	Std Parallel Farther from Equator	Latitude of Origin (see Note 5)
Lambert Equal-Area Meridional	LJ	Longitude of Central Meridian	Latitude of Proj. Origin	-	-
Mercator	MC	Longitude of Central Meridian	Latitude of True Scale	-	-
Miller Cylindrical	МН	Longitude of Central Meridian	Radius of Sphere (see Note 2)	-	-
French Lambert	MJ	Longitude of Proj. Origin	Latitude of Proj. Origin	Scale Factor at Proj. Origin	-
New Zealand Map Grid	NT	Longitude of Proj. Origin	Latitude of Proj. Origin	-	-
Oblique Mercator	OC	Longitude of Reference Point on Great Circle	Latitude of Reference Point on Great Circle	Azimuth of Great Circle at Reference Point	-
Orthographic	OD	Longitude of Proj. Origin	Latitude of Proj. Origin	-	-

TABLE F-5. DIGEST Projection Codes and Parameters - Continued.

PROJECTION	PROJ'N	EST Projection Co		TETERS	
	CODE	1	2	3	4
Polar Stereographic	PG	Central Meridian (Longitude straight down from Pole on map)	Latitude of True Scale	-	-
Polyconic	PH	Longitude of Central Meridian	Latitude of Proj. Origin	-	-
Relative Coordinates	RC	X-Scale Factor	Y-Scale Factor	-	-
Hotine Oblique Mercator (Rectified Skew Orthomorphic)	RS Alt:RB	Longitude of Proj. Origin	Latitude of Proj. Origin	Azimuth East of North for Central Line (Skew X-Axis) at Proj. Origin	Scale Factor at Proj. Origin
Robinson	RX	Longitude of Central Meridian	Radius of Sphere (see Note 2)	-	-
Sinusoidal	SA	Longitude of Central Meridian	Radius of Sphere (see Note 2)	-	-
Oblique Stereographic	SD	Longitude of Origin	Latitude of Origin	Scale factor at Origin	-
Space Oblique Mercator	SX	Application Code (see Note 3)	Vehicle Number (see Note 4)	Orbital Path Number (see Note 4)	
Transverse Mercator	TC	Longitude of Central Meridian	Central Scale Factor	Latitude of Origin (see Note 5)	-
Van der Grinten	VA	Longitude of Central Meridian	Radius of Sphere (see Note 2)	-	-
General Vertical Near- Side Perspective	VX	Longitude of Proj. Origin	Latitude of Proj. Origin	Height of Perspective Point above Surface (in metres)	-
Other Known Projection	ZY	-	-	-	-

Note 1. The parameters of the Lambert Conformal Conic projection are based on the version derived from 2 Standard Parallels. Where the projection is derived from a single standard parallel with a scale factor, data producers need to compute the equivalent parameters for the 2-standard-parallel case.

Note 2. This radius can be omitted if the chosen sphere has the same surface area as the chosen ellipsoid. The radius R which has that property may be derived from the ellipsoid parameters as follows: Compute e^2 and e from $e^2 = 2*f - f^2$.

$$Qp = 1 - ((1-e^2)/(2*e))*Ln((1-e)/(1+e)).$$

 $R = a*Sqrt(Qp/2).$

Note 3. Application Code:

- 1 = "Landsat, USGS equations".
- 2 = "Landsat, EOSAT equations".

(Other values to be added as and when required.)

Note 4. These parameters combined with the Application Code determine the mathematical parameters used in the projection.

Note 5. The Origin included here is the point where Easting False Origin and Northing False Origin are applied, rather than the Projection Origin.

F.5.4 <u>Grid codes</u>. Table F-6 provides the allowable grids and their codes for the Grid System field. To assist the process of matching datums and projections to grids, datum codes and projection codes are shown in the last 2 columns.

It should be noted that some of the entries are **grid categories**, that is to say there is more than one possible grid. This can be due to more than one possible datum or more than one possible zone, or indeed both. In a small number of cases, a grid category covers zones which use different projections. Grid categories are marked with an asterisk (*).

In the context of a DIGEST dataset, the possible ambiguity of a grid category is resolved when the datum, projection and the values of the projection parameters are specified. Zone number may also be specified to improve identification.

Note the presence of special code MS for other known grid.

TABLE F-6. DIGEST Grid Codes.

GRID DESCRIPTION	GRID CODE	DATUM CODE	PROJ'N CODE
Aden Zone	AD		LE
Afghanistan Gauss-Krüger Grid	AF		TC
Air Defense Grid	AG		
Air Support Grid	AI		
Alabama Coordinate System * (see Note 2)	AJ		TC
Alaska Coordinate System * (see Notes 1 and 2)	AK		
Algeria Zone *	AL		MJ
Albania Bonne Grid	AM		BF
Alpha-Numeric (Atlas) Grid	AN		
Arbitrary Grid	AO		
American Samoa Coordinate System *	AP		LE
Argentine Gauss-Krüger Conformal Grid *	AQ		TC
Artillery Referencing System	AR		
Arizona Coordinate System * (see Note 2)	AS		TC
Australia Belt *	AU		TC
Arkansas Coordinate System * (see Note 2)	AV		LE
Australian Map Grid *	AW		TC
Azores Gauss Conformal Grid	AX	LOC	TC
Azores Zone	AZ	LOC	LE
Baku 1927 Coordinate System	BA		
Bavaria Soldner Coordinate System	BB		
Belgium Lambert Grid *	BC		
Belgium Bonne Grid	BE		BF

TABLE F-6. <u>DIGEST Grid Codes</u> - Continued.

GRID DESCRIPTION	GRID CODE	DATUM CODE	PROJ'N CODE
Brazil Gauss Conformal Grid *	BF		TC
Soldner-Berlin (Müggelberg) Grid	BL	RAU	
Borneo Rectified Skew Orthomorphic Grid *	ВО		RS
British West Indies Grid *	BW		TC
California Coordinate System * (see Note 2)	СВ		LE
Canada British Modified Grid	CD		
Ceylon Belt (Transverse Mercator)	CE	IND	TC
Canary Islands (Spanish Lambert Grid)	CF		
Chile Gauss Conformal Grid *	CG		TC
China Belt *	СН		TC
Canary Islands Zone	CI		LE
China Lambert Zone	CJ		LE
Colorado Coordinate Zone * (see Note 2)	CK		LE
Connecticut Coordinate System *	CM		LE
Caspian Zone	CN		LE
Costa Rica Lambert Grid	CO	OCO	LE
Crimea Grid	CQ		LE
Crete Zone	CR		LE
Cuba Lambert Grid *	CT	NAS	LE
Caucasus Zone	CU	NAH	LE
Cape Verde Islands Zone	CV		LE
British Cassini Grid *	CW	OGB	CS
Czechoslovak Uniform Cadastral Coordinate System	CX		
Cyprus Grid *	CY		CS
Czechoslovak Military Grid	CZ	HER	OG
Danube Zone	DA	GRK	LE
Dahomey Belt	DB		
Denmark General Staff Grid	DC		
Delaware Coordinate System *	DD		TC
Dominican Lambert Grid	DE		LE
Denmark Geodetic Institute System 1934	DJ		BE
Cape Verde Peninsula Grid	DK		
East Africa Belt *	EA		TC
English Belt	EB		TC
Egypt Gauss Conformal Grid *	ED		TC
El Salvador Lambert Grid	EE		LE
Estonian Grid	EF		
Hungarian Unified National Mapping System (EOTR)	EO	HUY	TC
Egypt Purple Belt	EP		TC
Egypt Red Belt *	ER		TC
Egypt 35 Degree Belt	ET	OEG	
Fernando Poo Gauss Grid	FA		
Fiji Grid	FB		
Florida Coordinate System * (see Notes 1 and 2)	FC		
French Bonne Grid	FD		BF
French Guiana Gauss Grid	FE		TC
French Somaliland Gauss-Laborde Grid	FF		
French Indochina Grid	FI		

TABLE F-6. <u>DIGEST Grid Codes</u> - Continued.

GRID DESCRIPTION	GRID CODE	DATUM CODE	PROJ'N CODE
Franz Josef Land Zone	FJ		LE
French Lambert Grid *	FL		MJ
Formosa (Taiwan) Gauss-Schreiber Coordinate System	FO		
French Equatorial Africa Grid	FS		
Gabon Belt *	GA		TC
Gauss-Boaga Grid (Transverse Mercator)	GB	EUR	TC
Gabon Gauss Conformal Grid	GC		TC
Geographic Reference System (GEOREF) *	GE		
Guadeloupe Gauss-Laborde Grid	GF		
Colombia Gauss Conformal Grid	GG	BOO	TC
Sweden Gauss-Hannover Grid	GH		TC
Georgia Coordinate System * (see Note 2)	GI		TC
Gauss-Krüger Grid (Transverse Mercator) *	GK		TC
Greece Azimuthal Grid	GL		
German Army Grid (DHG) *	GN		TC
Ghana National Grid	GO		TC
Greece Bonne Grid	GP		BF
Greece Conical Mecklenburg Coordinates	GQ		LE
Greece Conical Mecklenburg Coordinate (New	GR		LE
Numbering)			
Greenland Lambert Grid	GT	NAS	LE
Guinea Zone	GU		LE
Guam Coordinate System	GV		
Guatemala Lambert Grid	GW		LE
Guyana Transverse Mercator Grid	GY	LOC	TC
Haiti Lambert Grid	HB		LE
Hawaii Coordinate System * (see Note 2)	HC		TC
Hawaii Grid	HD		
Honduras Lambert Grid	HE		LE
Hong Kong New System Cassini Grid	HF	HKO	CS
Hungary Stereographic Grid	HG	LOC	
Hong Kong Colony Grid	HR		
Idaho Coordinate System * (see Note 2)	IA		TC
Illinois Coordinate System * (see Note 2)	IB		TC
Indiana Coordinate System * (see Note 2)	IC		TC
Indonesia Mercator Grid	ID		MC
Indonesia Polyhedric Grid *	IE		
Iowa Coordinate System * (see Note 2)	IF		LE
Ivory Coast Azimuthal Grid	IG		
Irish Cassini Grid	IH	EUR	CS
Ivory Coast Belt	IJ		
Irish Transverse Mercator Grid	IK	IRL	TC
Iceland New Lambert Zone	IL	НЈО	LE
India Zone *	IN		LE
Iberian Peninsula Zone	IP		LE
Iraq Zone *	IQ		LE
Iraq National Grid	IR		TC
Italy Zone *	IT		LE

TABLE F-6. <u>DIGEST Grid Codes</u> - Continued.

GRID DESCRIPTION	GRID CODE		PROJ'N CODE
Ivy - Found on an HA in Marshall Islands	IY		
Iceland Zone	IZ	НЈО	LE
Jamaica Foot Grid	JA		LE
Japan Plane-Rectangular Coordinate System	JB		
Japan Gauss-Schreiber Grid	JC		
Jamaica National Grid (metric)	JM		LE
Johore Grid	JO		CS
Austria Gauss-Krüger Grid	KA		TC
Bulgaria Gauss-Krüger Grid	KB		TC
Katanga Grid	KC		
Kansas Coordinate System * (see Note 2)	KD		LE
Kentucky Coordinate System * (see Note 2)	KE		LE
Finland Gauss-Krüger Grid	KF		TC
German Gauss-Krüger Grid	KG		TC
Kenya Colony Grid	KH		CS
Korea Gauss-Schreiber Coordinate System	KJ		
Louisiana Coordinate System * (see Note 2)	KK		LE
Lithuania Gauss-Krüger Grid	KL		TC
Kwantung Province Grid	KN		
Turkey Gauss-Krüger Grid	KT		TC
Kwangsi Province Grid	KW		
Luxembourg Gauss-Krüger Grid	KX	EUR	TC
Lambert Conformal Conic Grid *	LC		
Latvia Coordinate System	LD		
Levant Zone	LE	EUR	MJ
Levant Stereographic Grid	LF		
Liberia Rectified Skew Orthomorphic Grid	LG		RS
Libya Zone	LI	EUR	LE
Sirte (Libya) Lambert Grid	LL		LE
Malaya Grid *	MA		CS
Malta Belt	MB	LOC	TC
Maldive-Chagos Belt	MC		TC
Madiera Zone	MD		LE
Mediterranean Zone *	ME		LE
Maine Coordinate System * (see Note 2)	MF		TC
Malaya Rectified Skew Orthomorphic (Yard) Grid	MG	KEA	RS
Martinique Gauss Grid	MH		TC
Maryland Coordinate System *	MI		LE
Massachusetts Coordinate System * (see Note 2)	MJ		LE
Mexican Lambert Grid	MK		LE
Michigan Coordinate System * (see Notes 1 and 2)	ML		
Mecca-Muscat Zone	MM		LE
Minnesota Coordinate System * (see Note 2)	MN		LE
Madagascar Grid (Laborde)	MO	TAN	LA
Mississippi Coordinate System * (see Note 2)	MP		TC
Morocco Zone *	MQ		MJ
Other Known Grid	MS		
Missouri Coordinate System * (see Note 2)	MT		TC

TABLE F-6. <u>DIGEST Grid Codes</u> - Continued.

		PROJ'N CODE
	DATOM CODE	LE LE
		LE
		LE
		PH
	MED	LE
	WEK	TC
		TC
	OCP	TC
	ООВ	LE
		LE
		LE
		TC
		LE
		TC
	DDM	TC
	PDM) (C
NM		MC
NO		207
		MJ
		TC
		TC
-		
		LE
	GEO	NT
		LE
NY		LE
NZ		TC
OA		
OB	OSL	TC
OD		LE
OE		LE
OR	NAS	
OS		LE
PA		TC
PB		LE
PC		CS
PD		TC
1		
PE		
PE PF		LE
PF		
PF PI	LUZ	PH
PF	LUZ	
	GRID CODE MU MV MW MW MX NA NB NC ND NE NF NG NH NI NJ NK NL NM NO NN NP NQ NR NS NT NU NV NW NX NY NZ OA OB OD OE OR OS PA PB PC PD	MU MV MW MW MX NA MER NB NC NB NC ND OGB NE NF NG NH NI NJ NI NJ NK NL PDM NM NO NN NP NQ NR NS NT GEO NU NV NW NX NY NZ OA OB OB OB OB OB OB PA PB PC PD

TABLE F-6. <u>DIGEST Grid Codes</u> - Continued.

GRID DESCRIPTION	GRID CODE		DE PROJ'N CODE
Philippine Polyconic Grid	PP	APL	PH
Portugal Bonne Grid, Old	PQ		BF
Portugal Bonne Grid, New	PR		BF
Portugal Gauss Grid	PS	LIS	TC
Puerto Rico & Virgin Islands Coordinate System *	PT		LE
Puerto Rico Lambert Grid	PU		LE
Qatar Cassini Grid	QA		CS
Qatar Peninsula Grid (or Qatar National Grid (TM))	QU	QAT	TC
Russian Belt *	RB	EUR	TC
Reunion Gauss Grid	RC		TC
Rhode Island Coordinate System *	RD		TC
Romania Bonne Grid	RE		BF
Soviet Coordinate System of 1942 *	RF	PUK	TC
Romania Lambert-Cholesky Grid	RH		
Rikets National Grid *	RK	STO	TC
Romania Stereographic Grid	RI		SD
Pulkovo Coordinate System of 1932	RT		
South Africa Belt (yards) *	SA		TC
Senegal Gauss Conformal Grid (Belt)	SB		TC
South Africa Coordinate System (South Africa Belt	SD		TC
(English feet)) *			
Senegal Belt	SE		TC
South Carolina Coordinate System * (see Note 2)	SF		LE
Sahara Zone	SH		LE
South Dakota Coordinate System * (see Note 2)	SI		LE
South Libya Zone	SJ		LE
Sarawak Grid	SK		CS
Spain Lambert Grid	SL	EUR	LE
Southern New Guinea Grid *	SN		LE
South Georgia Lambert Grid	SQ		LE
South Syria Lambert Grid	SR		LE
Spanish North-Morocco Lambert Grid	SS		LE
Svalbard Gauss-Krüger Grid	SV		TC
Svobodny 1935 Coordinate System	SX		
Seychelles Belt	SY		TC
Spitzbergen Zone	SZ		LE
Tanganyika Territorial Grid	TA		
Tashkent 1875 Coordinate System	ТВ		
Tennessee Coordinate System *	TC		LE
Texas Coordinate System * (see Note 2)	TD		TC
Tobago Grid	TE	MDT	CS
Trinidad Grid	TF		CS
Trucial Coast Cassini Grid	TG		CS
Trucial Coast Transverse Mercator Grid	TH		TC
Turkey Bonne Grid	TI		BF
Tunisia Zone *	TN		MJ
Uganda Cassini Coordinate System *	UA		CS
Unidentified Grid	UB		

TABLE F-6. DIGEST Grid Codes - Continued.

GRID DESCRIPTION	GRID CODE	DATUM CODE	PROJ'N CODE
Uruguay Gauss-Krüger Grid	UC		TC
Utah Coordinate System * (see Note 2)	UD		LE
Universal Polar Stereographic System *	UP		PG
(Note: 61 is recommended Zone Number for Northern			
Polar Zone, -61 for Southern Polar Zone)			
U.S. Polyconic Grid System	US	NAS	PH
Universal Transverse Mercator *	UT		TC
(Note: 1 to 60 are recommended Zone Numbers for			
Northern Zones, -1 to -60 for Southern Zones)			
Vermont Coordinate System *	VA		TC
Virginia Coordinate System * (see Note 2)	VB		LE
Venezuela Modified Lambert Grid	VE		
Vietnam Azimuthal Grid	VI		
West Malaysia Rectified Skew Orthomorphic (Metric)	WA		RS
Grid			
Switzerland Bonne Grid	WB		BF
Switzerland Conformal Oblique Cylindrical Grid	WC		OC
West Virginia Coordinate System *	WD		LE
Wisconsin Coordinate System *	WE		LE
Wyoming Coordinate System *	WF		TC
Washington Coordinate System * (see Note 2)	WH		TC
World Polyconic System	WP		PH
Yugoslavia Gauss-Krüger Grid (Not Reduced)	YA	HER	TC
Yugoslavia Reduced Gauss-Krüger Grid	YG	HER	TC
Yunnan Province Grid	YU		

^{*} grid category, covering more than one possible grid

Note 1. In this case, not all zones use the same projection.

Note 2. For US State plane coordinate systems with more than one zone, use of the 4-figure grid zone number given in FIPS 70-1 is recommended.

APPENDIX G

UNITS OF MEASURE CODES

G.1 SCOPE

TBD

G.2 APPLICABLE DOCUMENTS

The applicable documents in section 2 MIL-STD-2500B apply to this appendix.

G.3 DEFINITIONS

The definitions in section 3 MIL-STD-2500B apply to this appendix.

F.4 GENERAL REQUIREMENTS

DIGEST defines units of measurement as referenced by ISO 1000 "SI units and recommendations for the use of their multiples and of certain other units." However, there are certain units outside the SI (Système international), some of which are recognized by International Committee for Weights and Measures (CIPM), which need to be included in DIGEST because of their practical importance, i.e. occurrence in DGI datasets. These units have their codes enclosed by parentheses ().

When a compound unit is formed by multiplication of two or more units, it can be indicated in one of the following ways:

$$N \cdot m$$
 or $N m$

DIGEST preference is "N \cdot m" to avoid misinterpretation of the blank space.

When a compound unit is formed by dividing one unit by another, it can be indicated in one of the following ways:

m or m/s or m s-1

S

The DIGEST preference is "m/s".

Table G-1 lists the SI, and commonly recognized (shown in parentheses), units of measure which are most likely to occur within a DIGEST dataset, and their codes (abbreviations) for the various Units of Measure fields of the Data Set Parameter Group.

TABLE G-1. DIGEST Unit of Measure Codes.

UNITS	CODE
LENGTH	
Micrometres	UM
Millimetres	MM
Centimetres	CM
Decimetres	DM
Metres	M
Kilometres	KM
Inches	(IN)
	LENGTH Micrometres Millimetres Centimetres Decimetres Metres Kilometres

TABLE G-1. DIGEST Unit of Measure Codes - Continued.

	TABLE G-1. <u>DIGEST Unit of Measure Codes</u> - Co		
	UNITS	CODE	
8.	Feet	(FT)	
9.	Yards	(YD)	
10.	Fathoms	(FM)	
11.	Fathoms and Feet	(FF)	
12.	Statute Miles	(MI)	
13.	Nautical miles	(NM)	
	TIME		
14.	Seconds	S	
15.	Minutes	MIN	
16.	Hours	Н	
17.	Days	D	
	SPEED		
18.	Metres per Second	M/S	
19.	Kilometres per Hour	KM/H	
20.	Miles per Hour	(MPH)	
21.	Knots	(KNOT)	
	AREA		
22.	Square metres	(M2)	
23.	Square kilometres	(KM2)	
24.	Hectares	(HA)	
	ANGULAR MEASUREMENT		
25.	Mils	ML	
26.	Seconds (of arc)	(SEC)	
27.	Minutes (of arc)	(MA)	
28.	Degrees (of arc)	(DEG)	
	WEIGHT (MASS)		
29.	Kilograms	KG	
30.	Kips	(KIP)	
	PRESSURE		
31.	Millibars	MBAR	
32.	Hectopascals	HPA	
	ELECTRICITY		
33.	Volts	V	
34.	Kilovolts	KV	
35.	Watts	W	
36.	Megawatts	MW	
37.	Gigawatts	GW	
38.	Amperes	A	
39.	Hertz	HZ	
40.	Kilohertz	KHZ	
41.	Megahertz	MHZ	
	MISCELLANEOUS		
42.	Beds	(BED)	
43.	Features	(FEATURE)	
44.	Lanes/Tracks	(LANE/TRACK)	
45.	Levels	(LEVEL)	
46	Lines	(LINE)	
47.	Occults	(OCCULT)	

 $TABLE\ G\text{-}1.\ \ \underline{DIGEST\ Unit\ of\ Measure\ Codes}\ \text{-}\ Continued.$

	UNITS	CODE
48.	Percent	(%)
49.	Persons	(PERSON)
50.	Qualifiers	(QUALIFIER)
51.	Structures	(STRUCTURE)
52.	Vehicles	(VEHICLE)

Note: Codes enclosed in parentheses indicate non-ISO $1000~\rm units$. The parentheses themselves do not form part of the code.